

# **6G NEXT**

TOWARDS 6G SPLIT COMPUTING NETWORK APPLICATIONS USE CASES AND ARCHITECTURE

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### 6G NEXT – NATIVE EXTENSIONS FOR XR TECHNOLOGIES



- What are the demanding applications of the future?
  - HoloCom Holographic Communication
  - Smart Drones
- What are the technologies to cope with the requirements?
  - High speed backbone with split computing capability
  - Low-Latency Reliable Mobile Communications
  - Convergence of Computing and Communication

### **SMART DRONES - ANTI COLLISION SYSTEM**



6G NeXt is going to implement a new kind of Anti Collision System

#### Mission:

- Observing the traffic situation and detecting / predicting dangerous situations in the vicinity of an aerodrome
- Calculate and fly the exit trajectory in case of near miss
- Calculation of the trajectory is off-loaded to the most appropriate part of cloud (split computing)



#### Innovation:

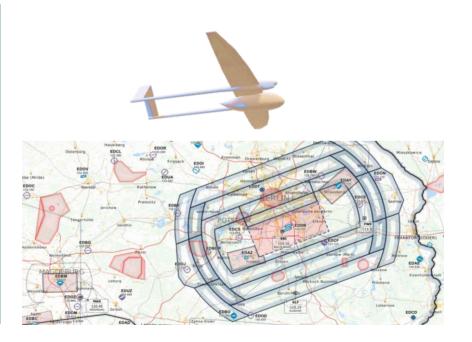
#### **Current TCAS**

- Pilots get a warning and in some situations recommendation to descend or to climb
- It is still in the responsibility of the pilot to steer the UAS/ airplane hopefully in the right way

 Our new 6G-based TCAS calculates exact flight routes and controls drones actively by taking aerodrome traffic into account

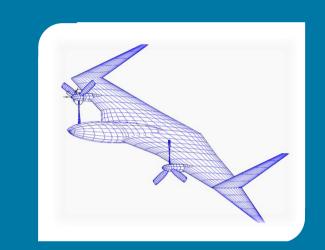
New method

 The calculation of the flight way is off-loaded to the most appropriate part of cloud





### **DIGITAL TWIN OF UAVS**



Calculation of trajectories requires a digital representation of every drone within the Anti-Collision System with all relevant parameters.

This enables simulation of critical situations in a virtual space

- Research on anti collision algorithm with fast moving UAVs
- Study on latency and reliability in 5G/6G networks in high-speed situations
- Research on conflict situations between slow- and fast-moving UAVs.

- The Smart Drone application adds dynamic change in availability of connectivity and CPU need, (GPU) power and low latency in processing and transmission
- $\rightarrow$  computing and communication grow together



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### **EDGE-TO-CLOUD SERVERLESS PLATFORM**



#### **Compute: based on Function-as-a-Service (FaaS)**

- Parallel invocations handled elastically
- Pay-as-you-go → application service only needs resources while it is running (resource-conscious at the edge)

#### Data: State decoupled from compute

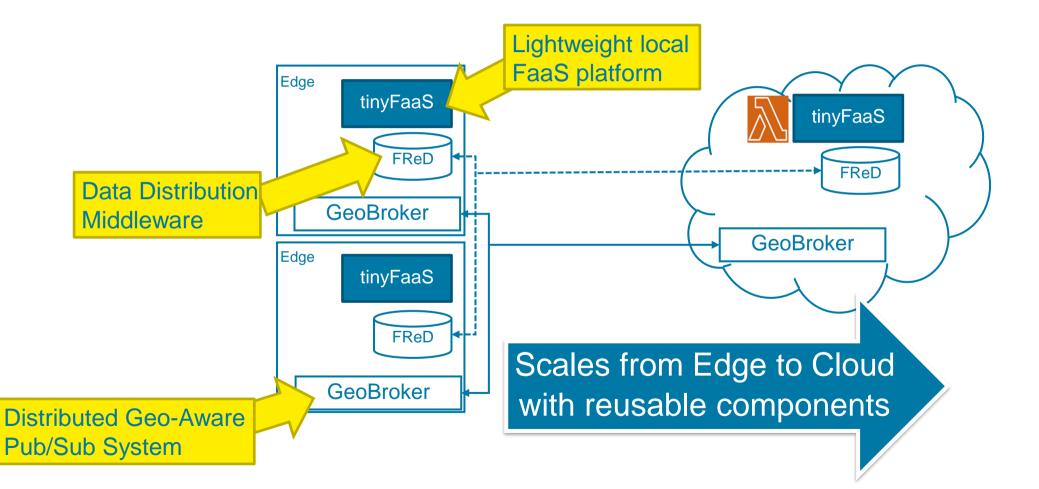
- Compute services can be scaled infinitely without consistency issues (handled by data platform)
- Data is distributed across regions efficiently (can be replicated with consistency)
- Data persistence is cheap at the edge (no running services needed)

#### **Communication: low-latency publish/subscribe system**

- Low-latency communication still needed
- Pub/sub paradigm makes integrating heterogeneous services easy
- "geo-aware" pub/sub limits message dissemination

### **EDGE-TO-CLOUD SERVERLESS PLATFORM**





### HOLOCOM FUTURE COMMUNICATION SERVICE



6G NeXt is going to implement a HOLOGRAPHIC 3D Chat with:

#### Natural eye focus

No glasses required. Eye accommodation (AKA eye focus) is not fixated on the physical display as in pure Stereoscopic 3D displays.

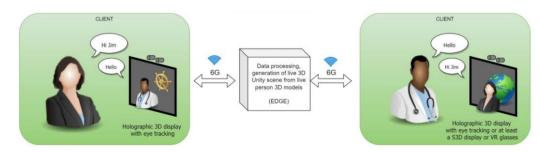
#### Natural depth

Image content is properly placed in space by real holograms – and crisply sharp at any depth.

#### Natural viewing

No difference to natural viewing for the human visual system – same depth cues provided.

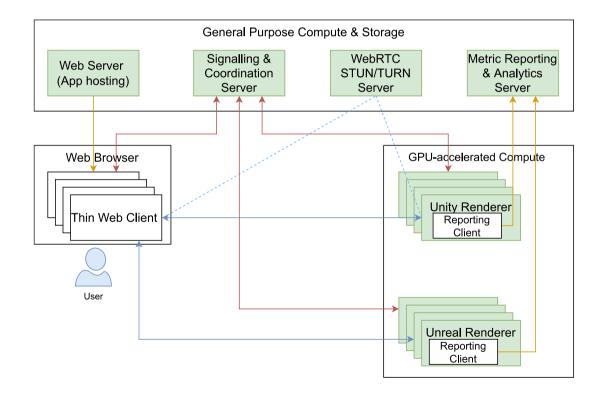




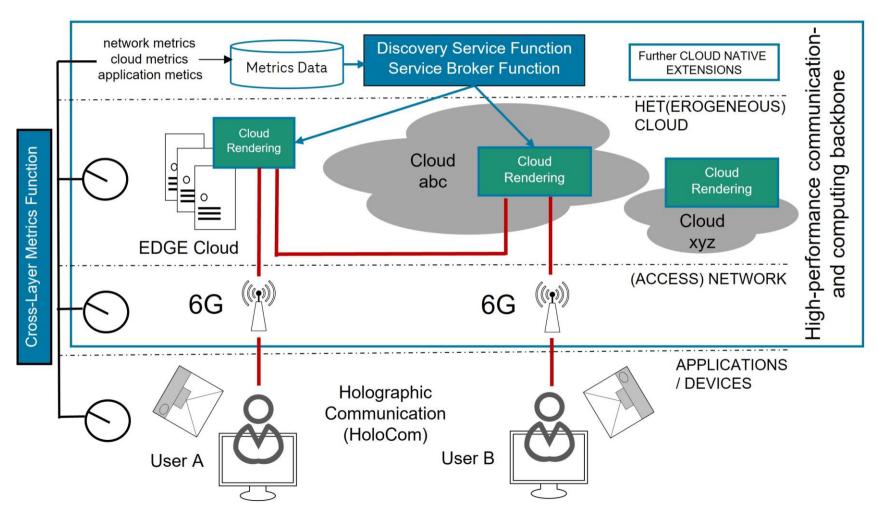
## **XR SPLIT RENDERING**



- Viewport Rendering and AI Processing tasks are crucial components affecting the 3D experience. Rendering photorealistic content requires advanced graphical processing which is not available on most consumer devices.
- Split Rendering solves this issue by offloading complex rendering and processing task to the network.
- Workloads must run efficiently on-device at low latency
  - Minimizing motion to photon latency is crucial for immersion



### **COMPUTING- AND NETWORK ARCHITECTURE**



Sergiy Melnyk et. Al. / 6G NeXt / Towards 6G Split Computing Network Applications 01.02.2023

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### **IMMERSIVE MEDIA COMMUNICATION QUALITY OF EXPERIENCE**

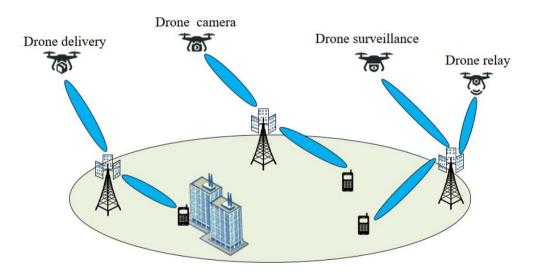


- User experience is central factor for real-time immersive media communication
  - Higher values of QoS not necessarily ensure higher values of QoE
  - Human perception is sensitive to certain display errors
  - User aspects must be included in the evaluation of HoloCom
- Subjective as well as objective metrics will be used for evaluation
  - Subjective measures include questionnaires related to co-presence, social presence, immersion,.
  - Overall mean opinion score will be computed
  - Conversational and behavioral data of the participants will be recorded for indirect evaluation of user experience
- Objective measures will be computed to evaluate 3D rendering, encoding and decoding of conversational partner

### **RADIO ACCESS NETWORK**

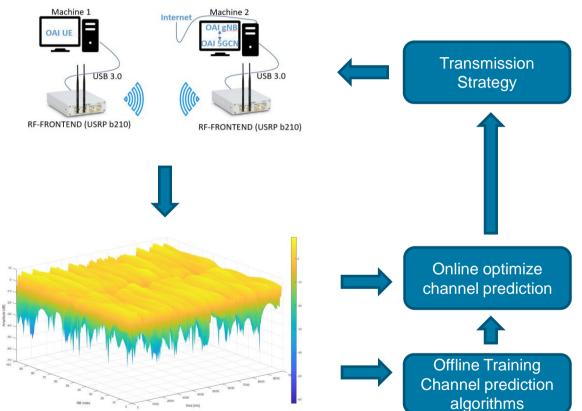


- Channel prediction
  - Frequent pilot transmission overhead due to channel phase variation
  - Using historical CSI to predict the future CSI by deep learning based time series prediction algorithms
- Beam-Tracking
  - Fully exploit the beamforming gain and provide 3D radio coverage
  - Obtain accurate CSI by serving ground Base station
  - Simultaneously track the azimuth and elevation angles of their LoS links with UAVs
- Forecast future CSI in advance with a time span that counteracts the induced delay.



### and improve throughput

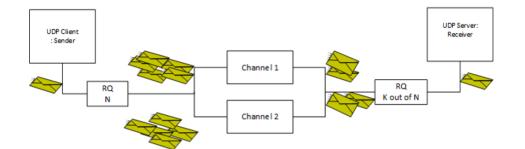
- Design appropriate channel prediction model
- Integrate channel prediction model to real platform
- Optimise transmission strategy based on predictions
- $\rightarrow$  Decrease error rate and improve throughput.

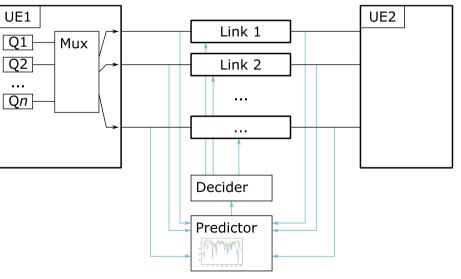




### **RADIO ACCESS NETWORK**

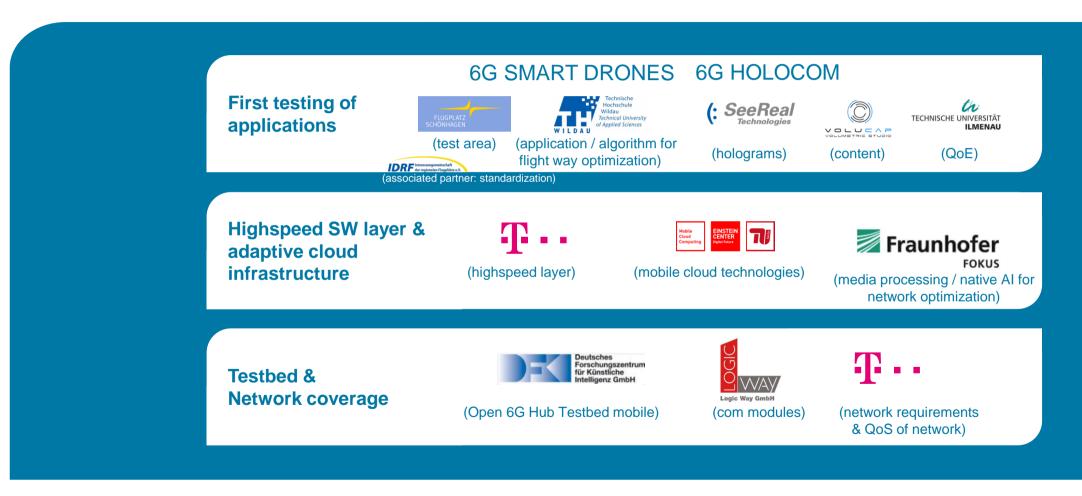
- Fountain coding (i.e. RaptorQ)
  - Erasure channel
  - Generate as many code words as necessary
  - K-out-of-N decoding
- Multi-link communication
  - Transmission of code words over different links or RANs
  - Traffic classes for requirements mapping
  - Channel prediction-based decision making







### **CONCLUSION AND OVERVIEW**



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# **THANK YOU!**











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