

ML-Based C-DRX Configuration Optimization



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Content



- Motivation, background, and problem
- Our machine-learning-based solution
- Results, insights, and lessons learned
- Conclusions and future work

Motivation, Background, and Methodology



Motivation



- Discontinuous Reception (DRX) allows UE to check for incoming downlink traffic intermittently to reduce UE energy consumption
- DRX creates a trade-off between UE energy saving and delay or throughput
- Number of possible DRX configurations very large [1],[2] → difficult to choose

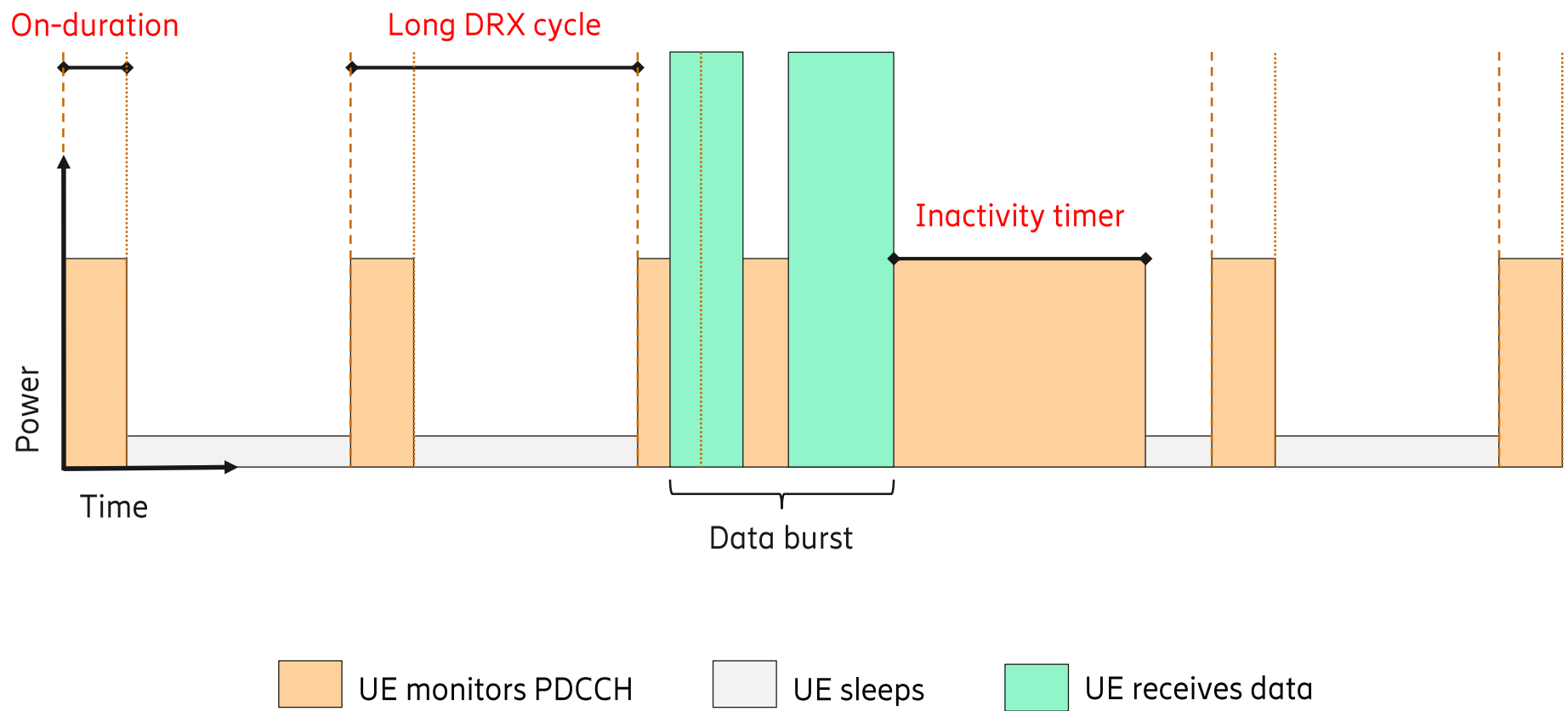
Goal of this work:

- Optimize DRX configuration per UE according to performance goals or intents using Machine Learning (ML) techniques
- Demonstrate value of energy-consumption-related feedback from UE

Connected Mode DRX



Long DRX cycle only



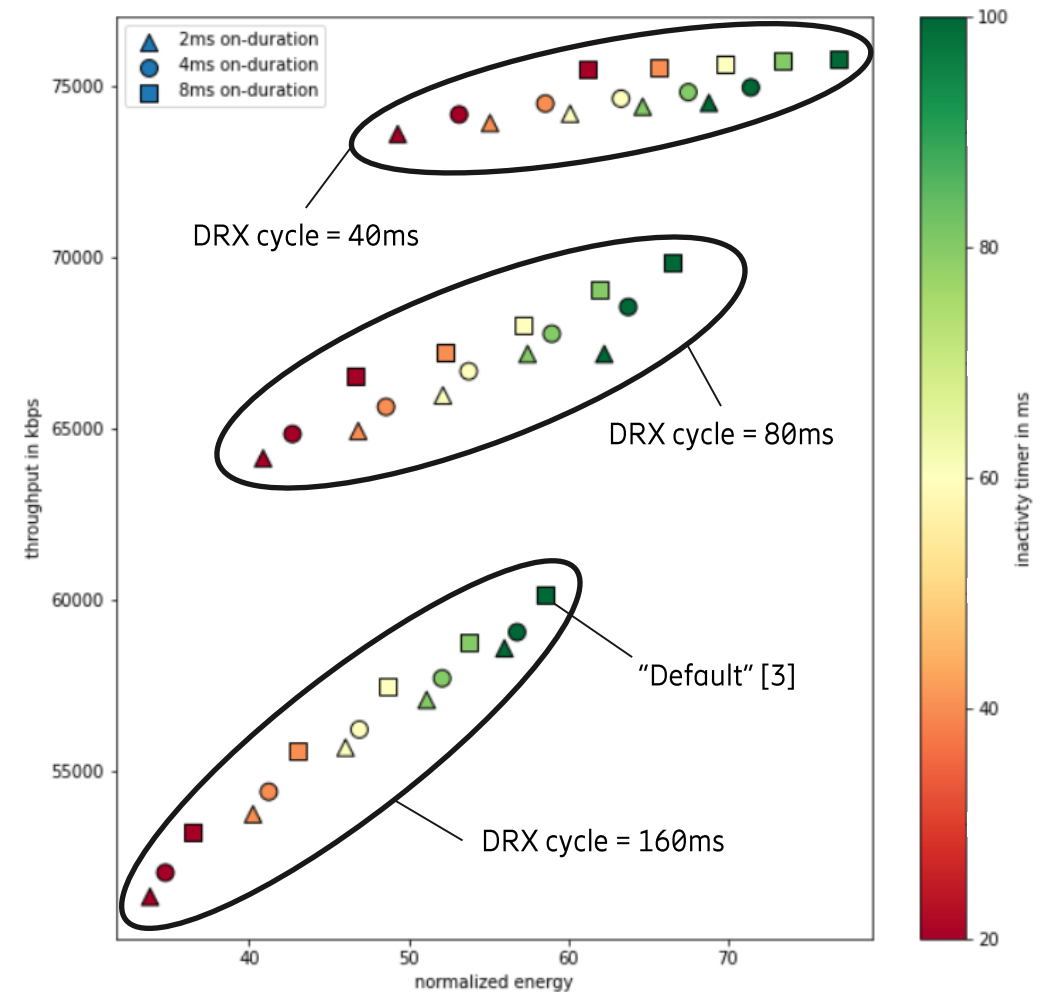
Related C-DRX Study

Default DRX setting according to 3GPP:

Long DRX cycle	160 ms
On-duration	8 ms
Inactivity timer	100 ms

FTP traffic model 3

- Packet size = 500 kB
- Mean inter-arrival time = 200 ms



Contextual Bandit



Approach:

Use contextual bandit to set optimal DRX configuration depending on UE energy consumption (and other) feedback

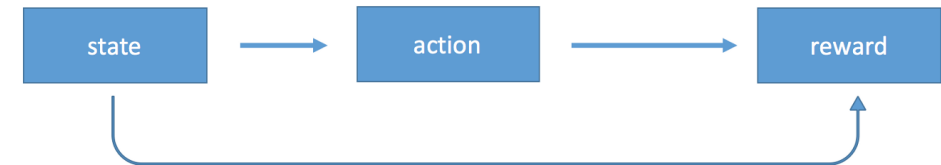
→ Realized using Vowpal Wabbit

Bandit behavior mainly affected by:

- Policy evaluation approach
→ Direct method
- Exploration strategy
→ Epsilon-greedy



“Contextual bandit is a machine learning framework designed to tackle [...] complex situations. [...] A learning algorithm can test out different actions and automatically learn which one has the most rewarding outcome for a given situation.” [4]



Contextual bandit problem, where state and action effect reward [5].

Exploration vs. Exploitation



“A learning algorithm can test out different actions and automatically learn which one has the most rewarding outcome for a given situation.”

ϵ -greedy

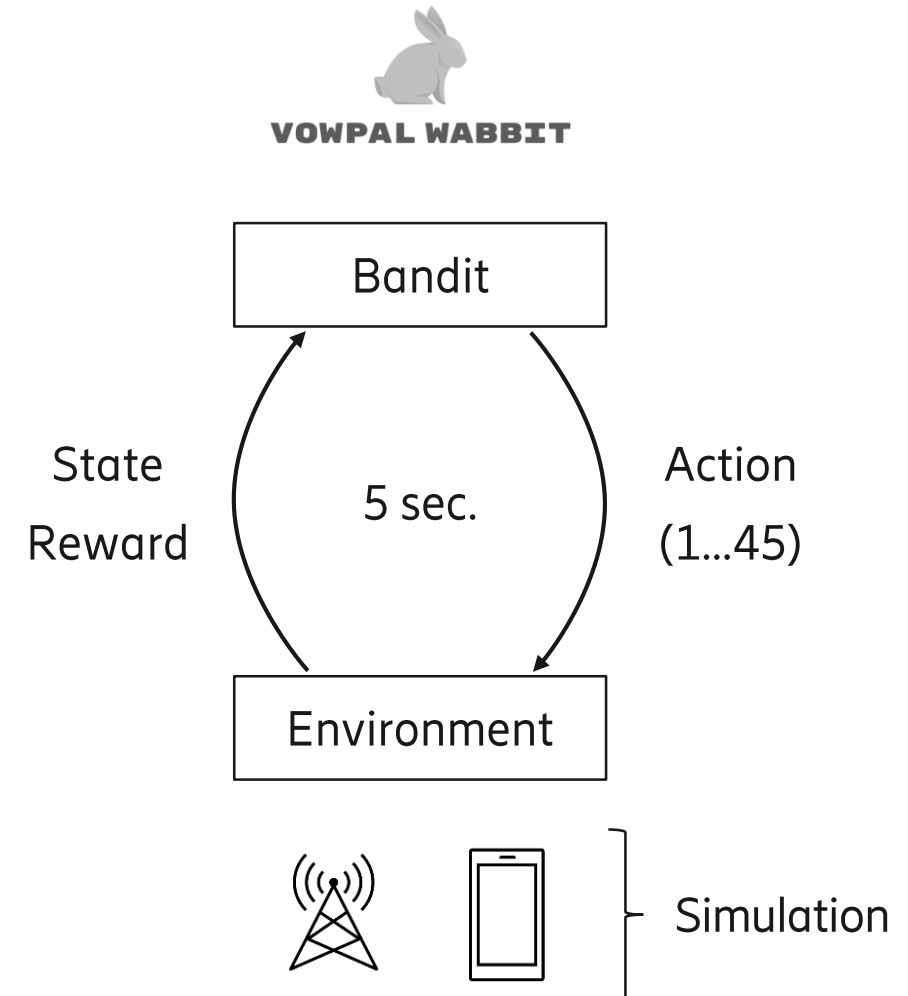
- Parameter ϵ controls trade-off between exploration vs. exploitation (for $0 < \epsilon < 1$)
- Exploitation with probability $1 - \epsilon$: Bandit chooses action based on (assumed) best reward
- Exploration with probability ϵ : Bandit chooses action uniformly at random
- ϵ can be fixed, adjusted over time (“ ϵ -decay”), or adapted in other ways, e.g., based on heuristics

Our choice: Linear “ ϵ -decay” from 100% to 5% during first 1000 learning steps

Observation-Action Cycle



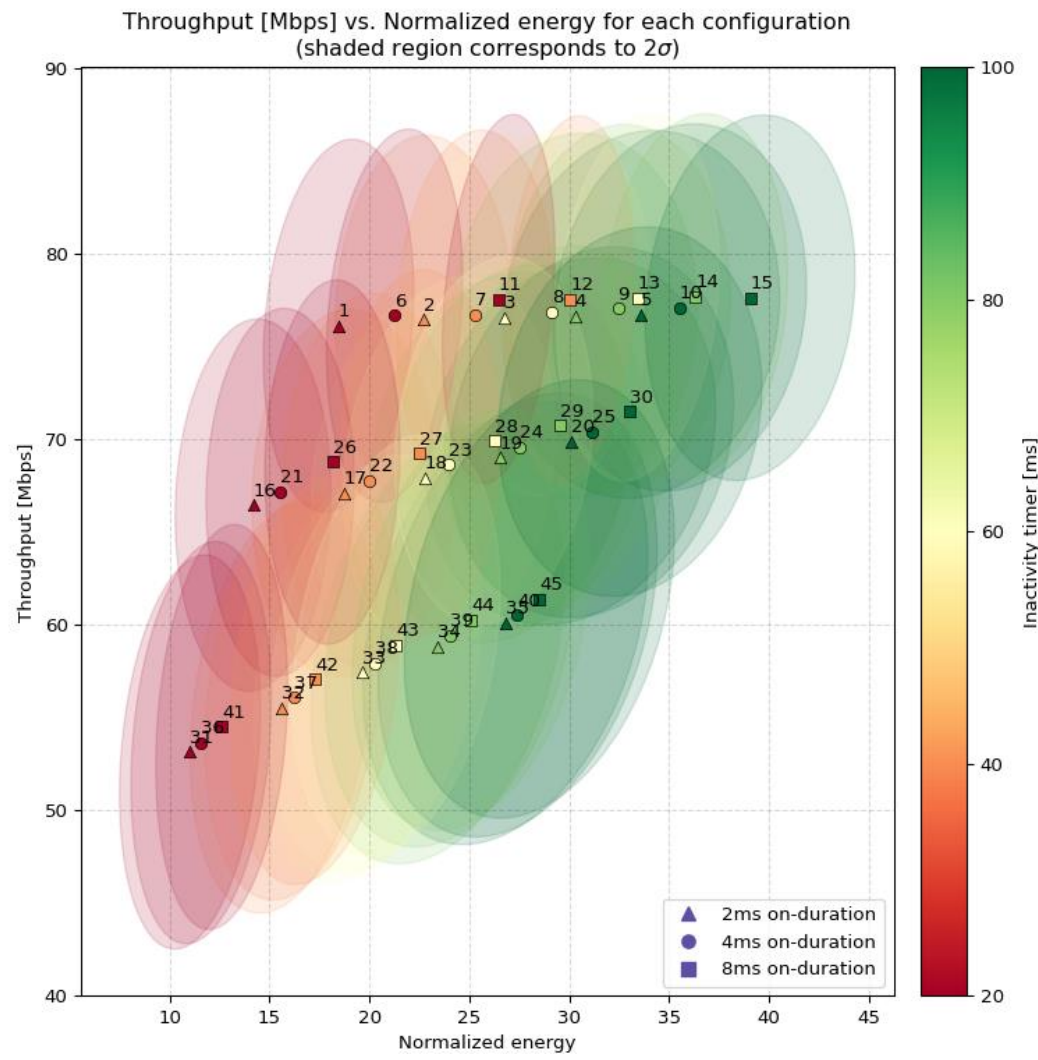
- State and reward created based on 5 sec. observation (5 sec. averaging period)
- Bandit chooses among 45 actions corresponding to 45 DRX configurations (labeled as 1...45)
- Chosen action is translated into DRX configuration upon actuation in simulation



Results and Insights



Statistics of the DRX configurations

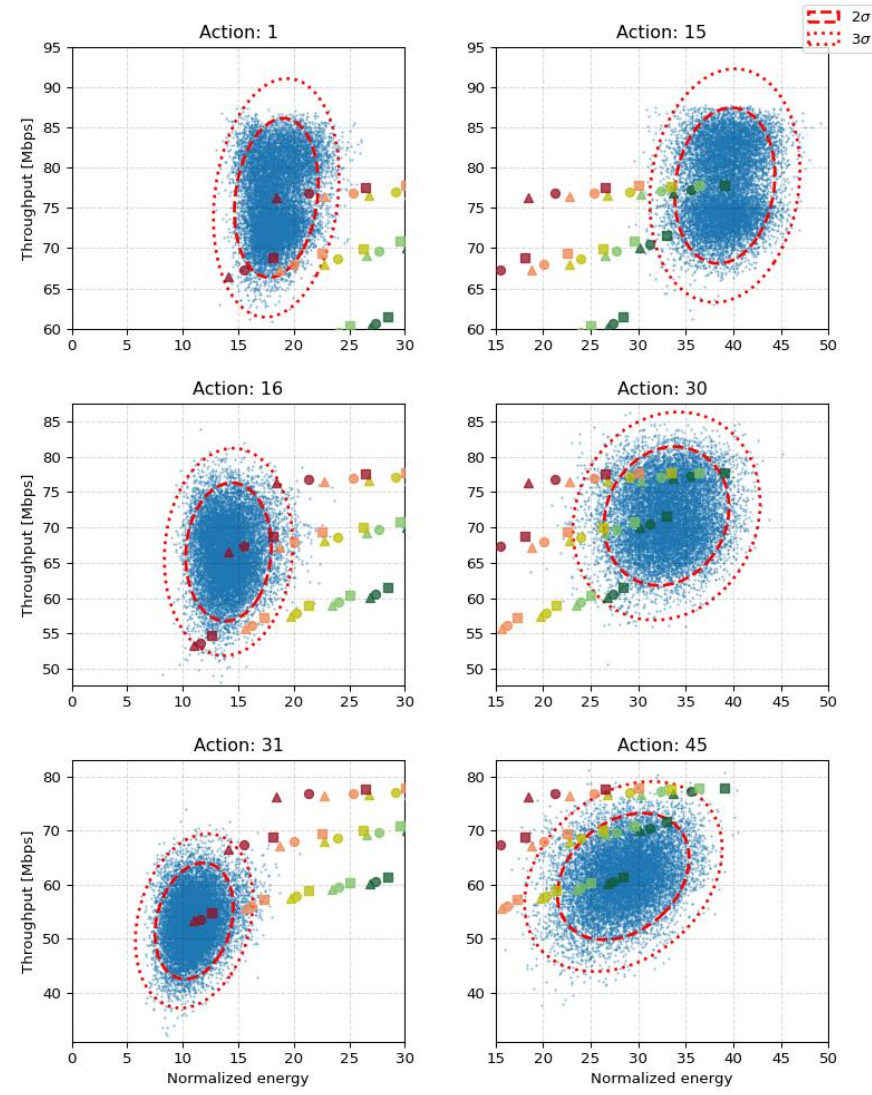


By choosing a certain DRX configuration (a.k.a. action 1-45) the UE experiences a variable throughput/energy consumption

The fine granularity of the different DRX parameters results in a large overlap between configurations

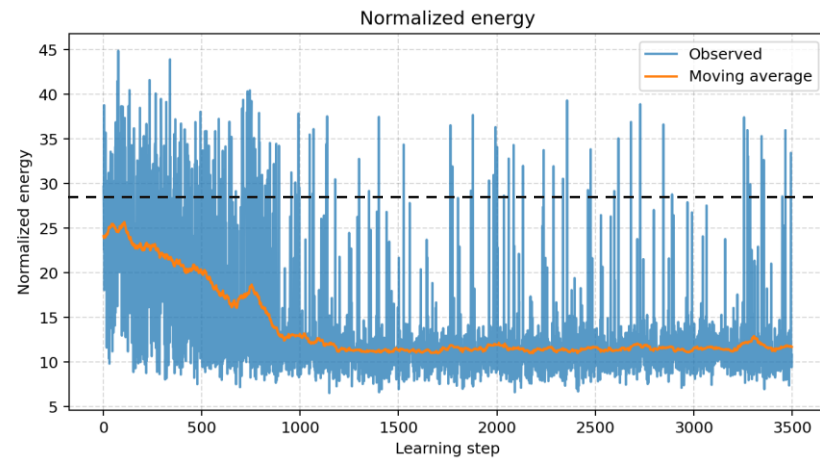


More in detail

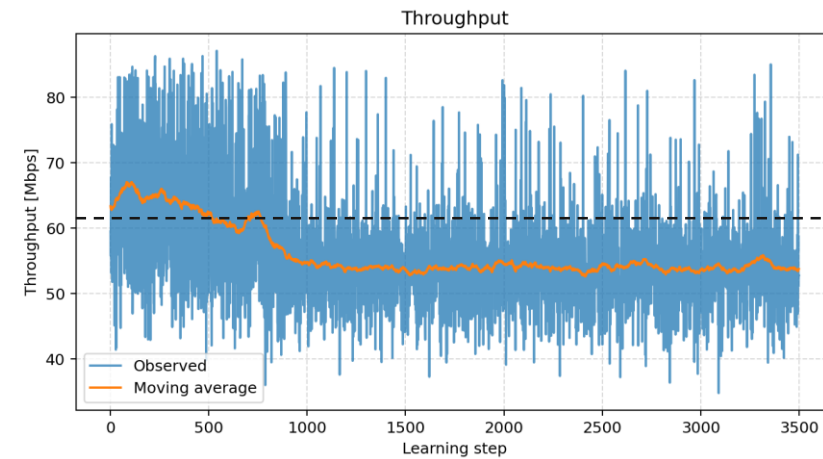
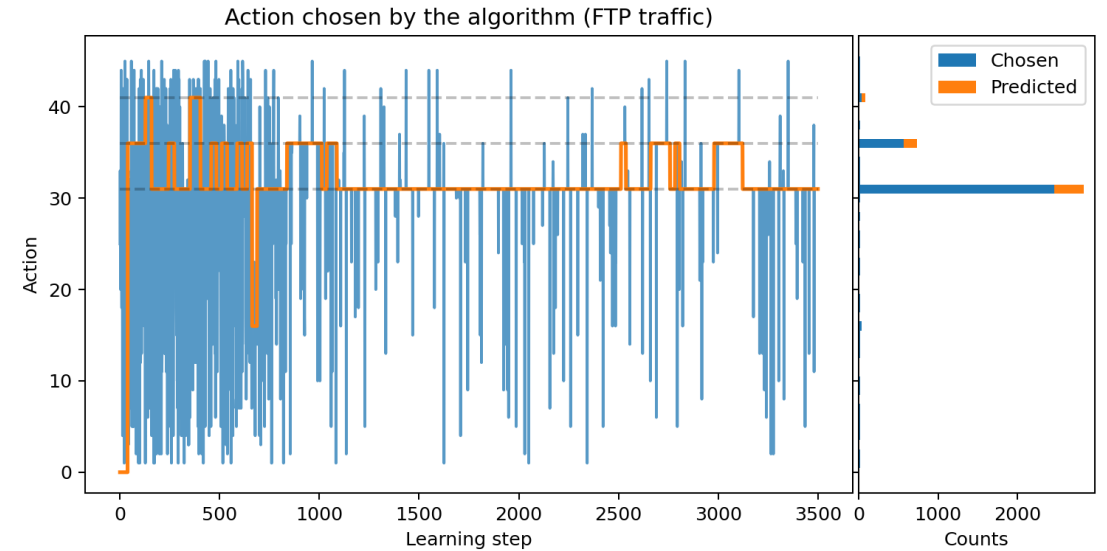


Experiment #1

- Traffic: FTP-3 model
- Intent: Energy minimization
- Reward $\sim Energy_{Monitor}^{-1} \in (0, 1)$



28.4 Units
Mean power of default DRX configuration (acc. 3GPP)



61.5 Mbps
Mean throughput of default DRX configuration (acc. 3GPP)

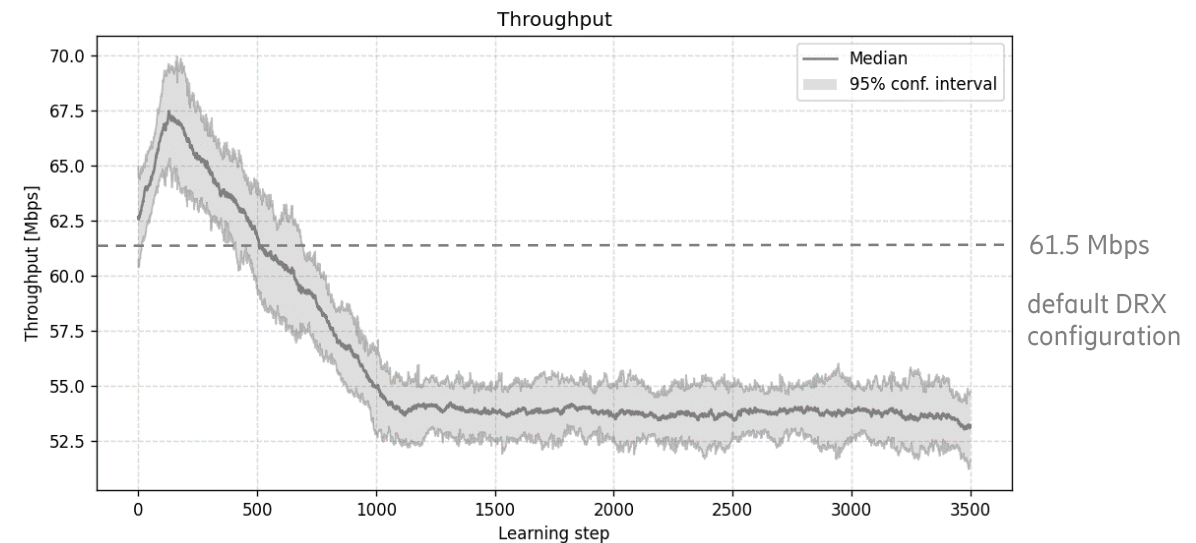
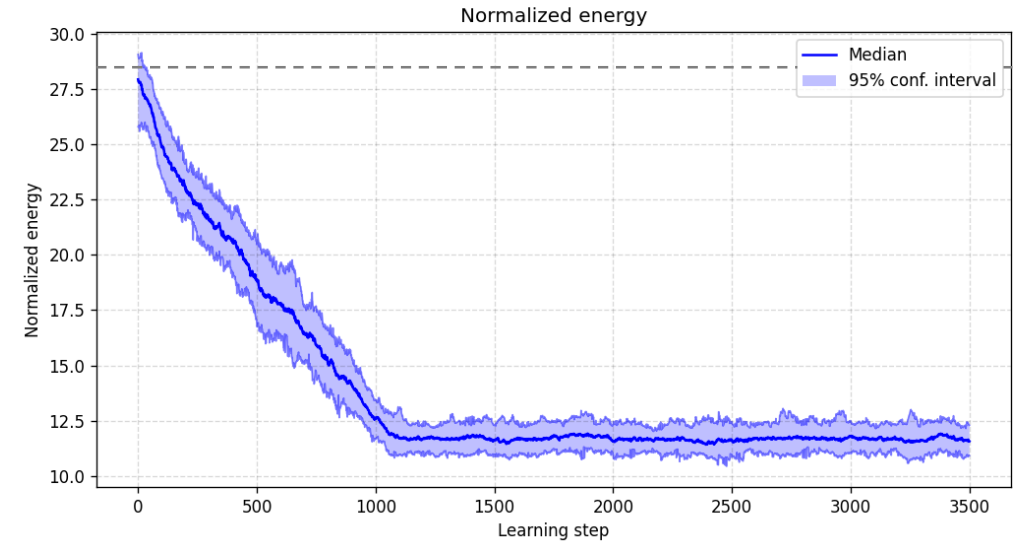
→ Compared to default DRX configuration, approximately 52% “useless” energy saving, but only 9% throughput loss.

Experiment #1

- Traffic: FTP-3 model
- Intent: Energy minimization
- Reward $\sim Energy_{Monitor}^{-1} \in (0, 1)$

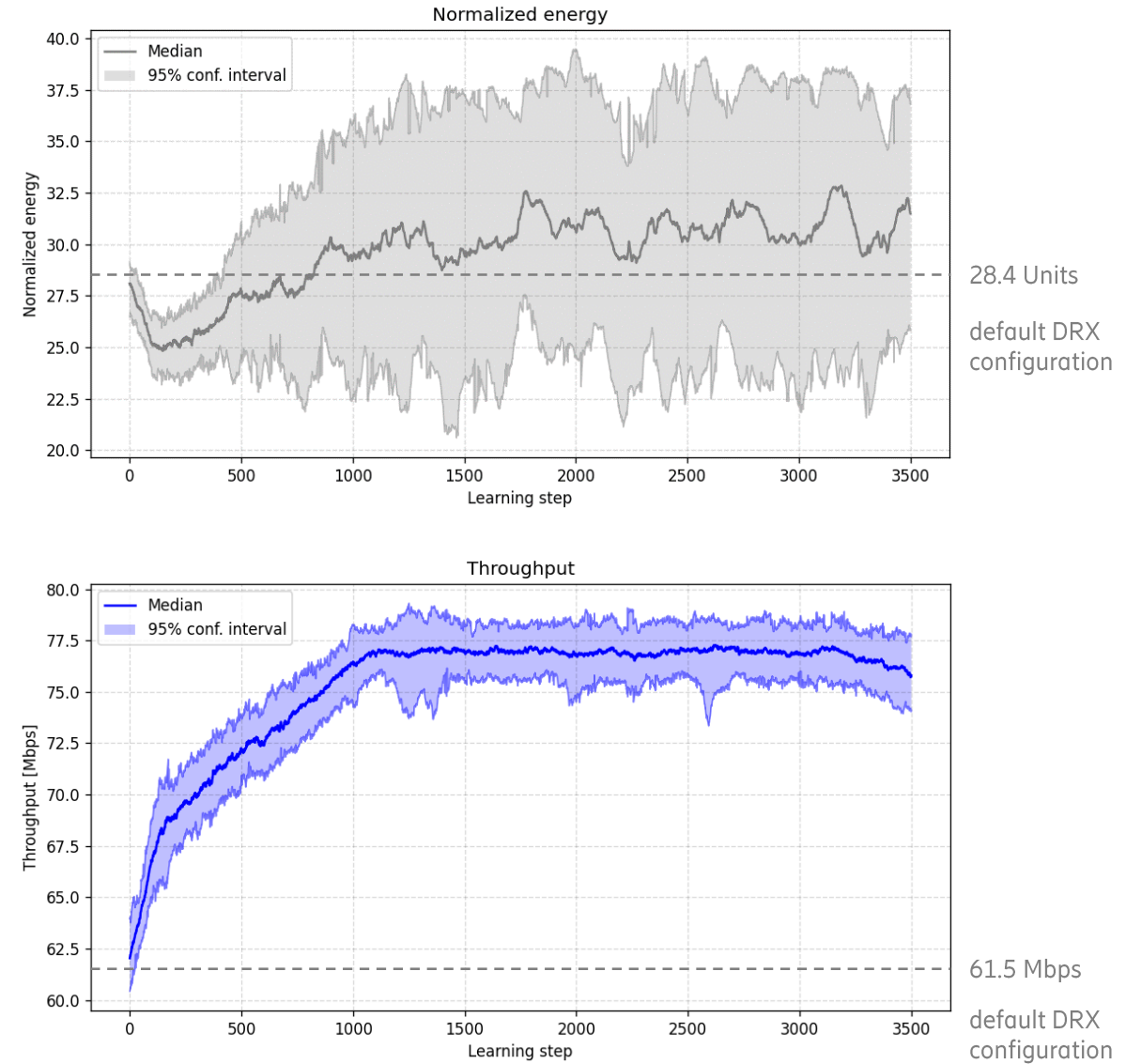
Simplified representation: Median and 95% confidence interval for 40 learning passes (with averaging window of 101 steps per simulation)

→ Reflects level of stability of learning



Experiment #2a

- Intent: Throughput maximization
- Reward $\sim \left(\frac{\text{Throughput}}{\text{Max. Throughput}} \right)^6 \in (0, 1)$
 - Non-linearity improves learning
- Observation: SINR
- Note: 37-71% correlation between throughput and SINR (mainly depending on the DRX cycle)

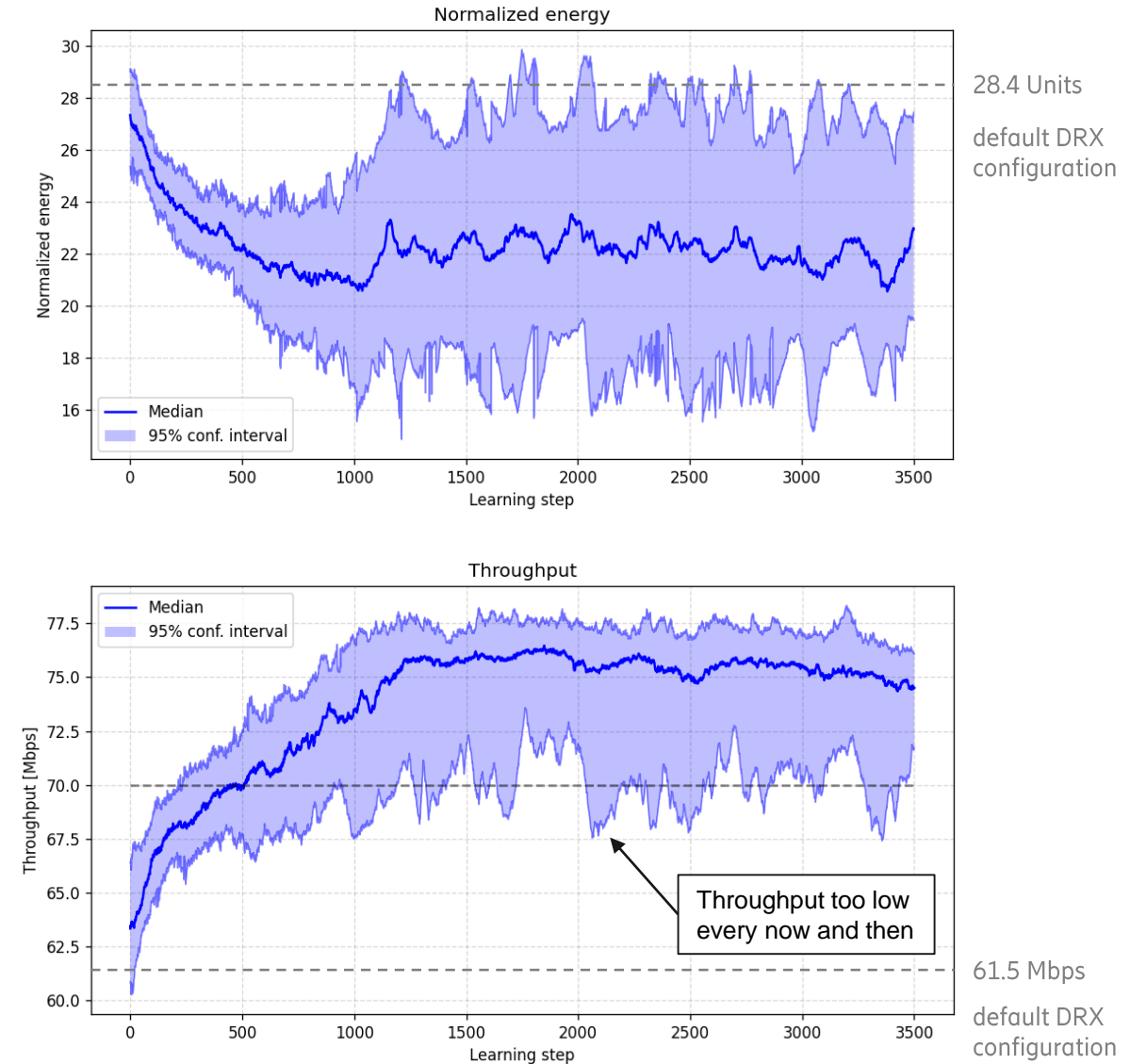


Experiment #3

- Intent: Performance-bounded energy minimization
- Constraint: Throughput min. 70 Mbps
- Reward $\begin{cases} \sim Energy_{Monitor}^{-1} & \text{if } TP \geq 70 \text{ Mbps} \\ -1 & \text{if } TP < 70 \text{ Mbps} \end{cases}$

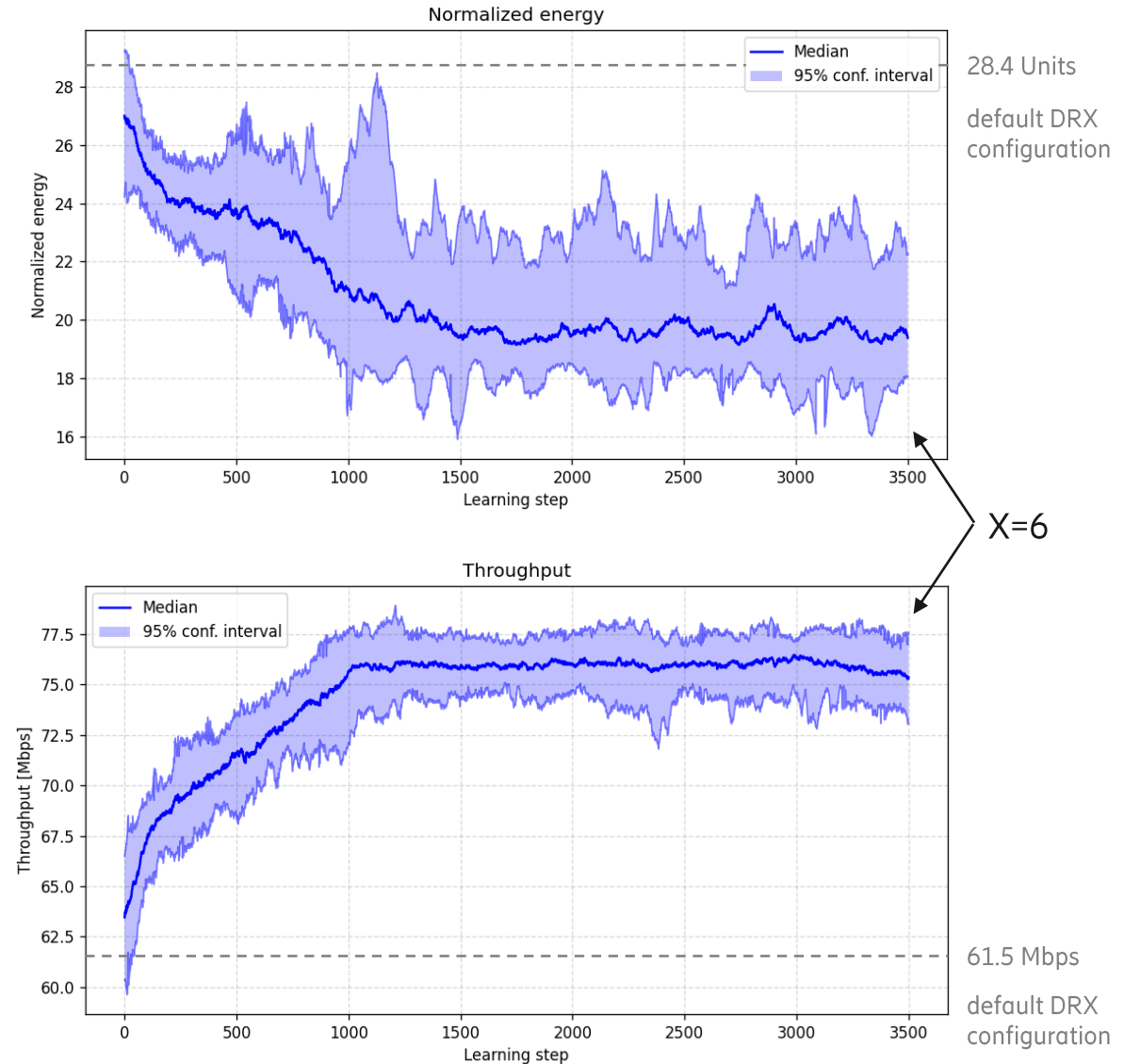
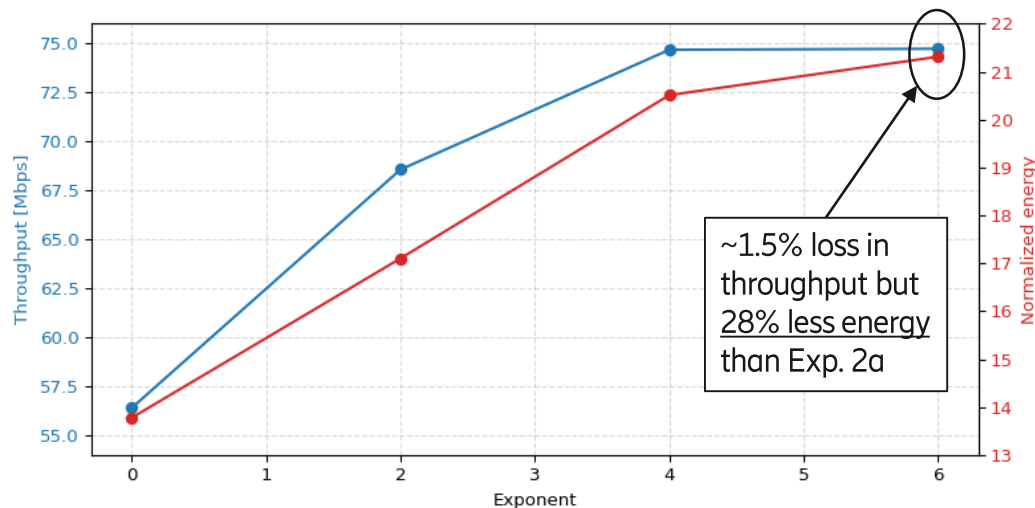
Compared to Exp. 2a:

→ Throughput loss 2.4%; Energy saving 26.2%



Experiment #4

- Intent: Adjustable joint optimization
- Reward $\sim Energy_{Monitor}^{-1} * \left(\frac{Throughput}{Max.Throughput} \right)^X$
- Varying the exponent, we give more or less relevance to maximizing throughput



Closing Remarks



Takeaways



Contextual bandit fast and simple approach to select good DRX configuration according to UE feedback

Randomness in rewards increases uncertainty and impairs convergence/stability

Hard performance bounds cause rewards that make learning more challenging

Multiple types of users (e.g., multiple types of traffic and intents) can be handled simultaneously

Future work:

- Consider other traffic types (e.g., real-time video)
- Explore softer thresholds
- Perform safe exploration

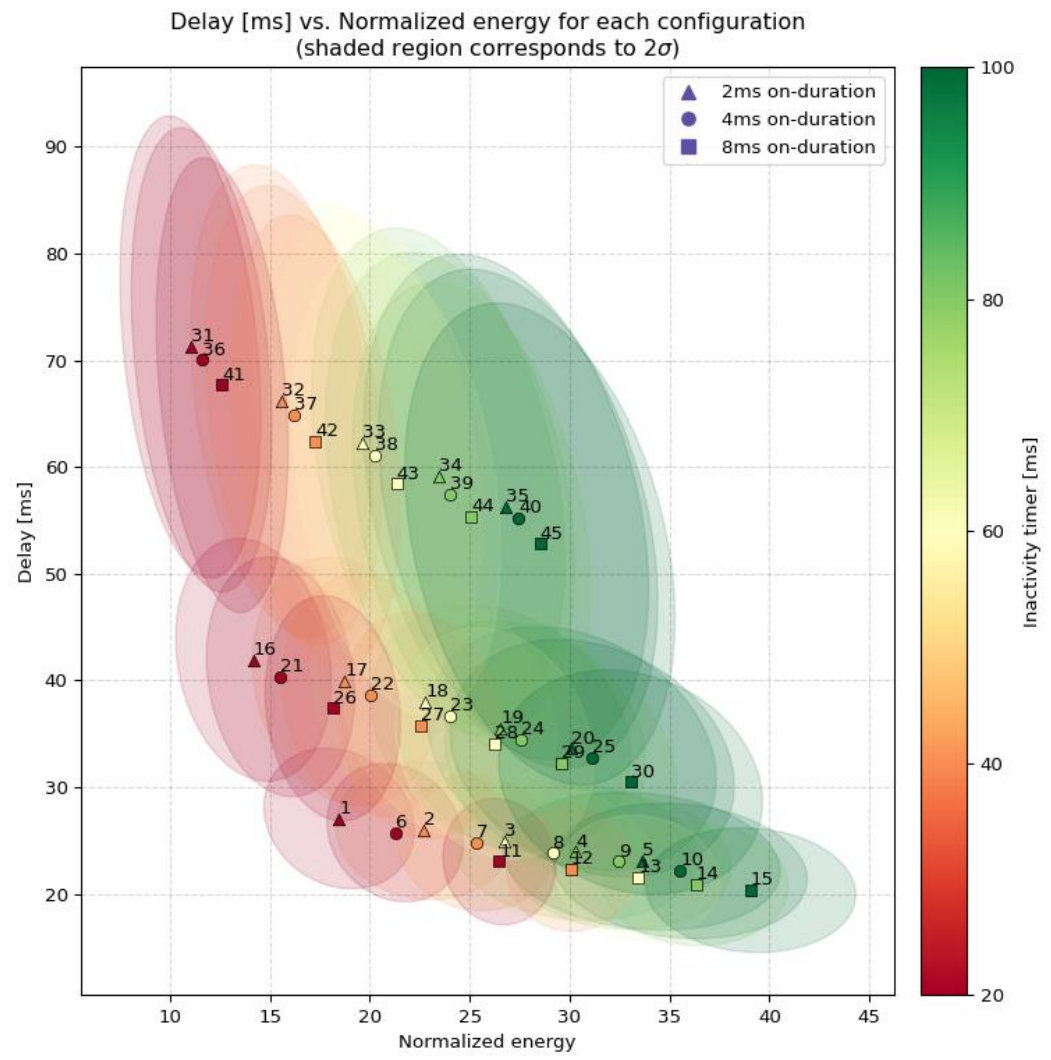


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Additional Slides

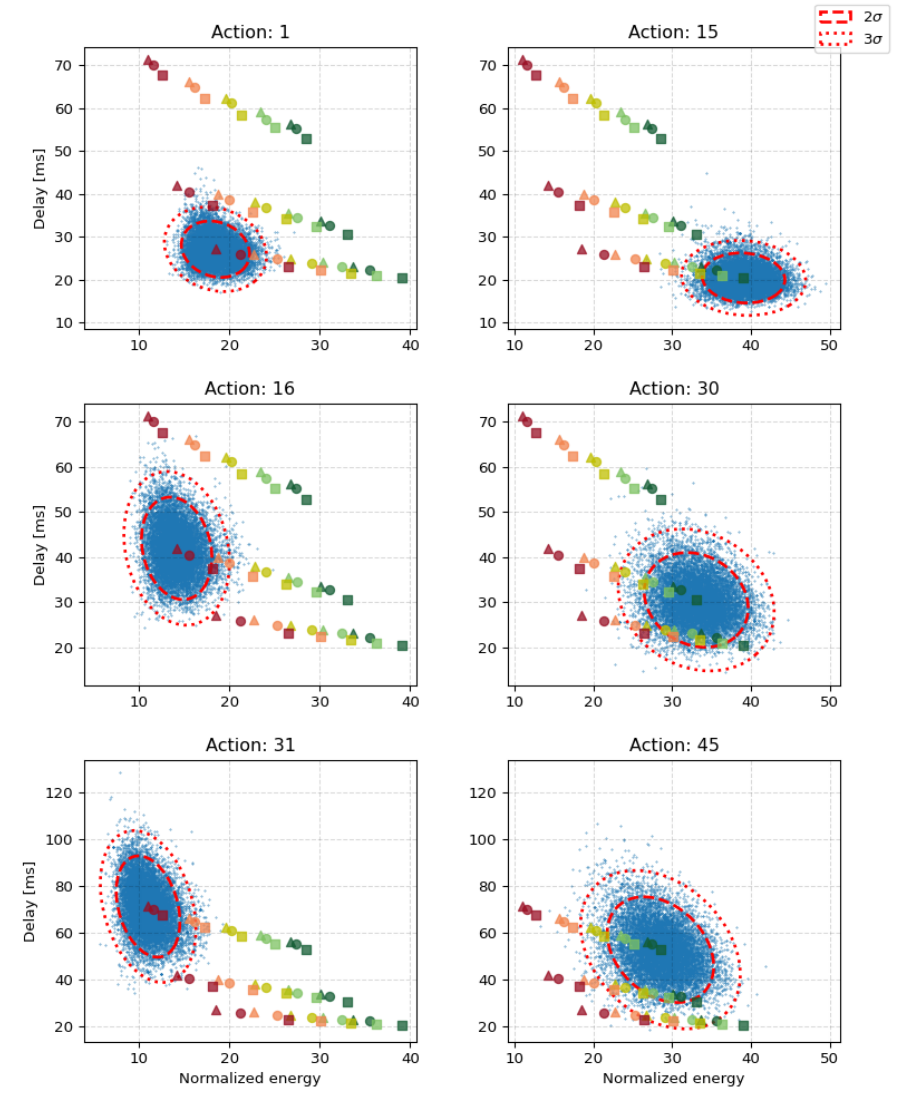
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By choosing a certain DRX configuration (a.k.a. action 1-45) the UE experiences a variable delay/energy consumption

The fine granularity of the different DRX parameters results in a large overlap between configurations

More in detail →



Experiment #2b

- Intent: Delay minimization
- Reward $\sim \frac{\text{Min. Delay}}{\text{Delay}} \in (0, 1)$

“Start delay” refers to delay of first segment of object transmission → Uncorrelated with SINR

