# Path Loss Models for Low-Power Wide-Area Networks: Experimental Results using LoRa

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Motivation

Related Work

Measurement Setup

Results

Conclusion and Future Work

References

Long Range IoT Networks are moving more and more into the centre of attention.

- Network-Protocol, Software, Hardware
  - Intelligent Gateway Placement?







### Forecasting Appropriate Locations

> Multiple water-sensors along a river: Waterlevel, Temperature



# Forecasting Appropriate Locations

- Using LoRa as example technology:
- Predicting signal strength.
- Find locations for necessary gateways.







- Measurements in the city of Oulu (Car/Boat) [1]
- Regression analysis

$$PL_{coeff} = 128.95 + 10 * 2.32 * log_{10}(\frac{d}{d_0})$$



Signal reception (Oulu) [1]









- Measurements in Dortmund [2]
- Regression analysis

$$PL_{coeff} = 132.25 + 10 * 2.65 * log_{10}(\frac{d}{d_0})$$

## Dortmund [2]:

- Okumura Hata Model
- ITU-Advanced Channel Model for Urban Macro NLOS Areas
- Winner+ Channel Models for Urban Macro NLOS Areas
- 3GPP Spatial Channel Model for Urban Macro Areas
- Oulu channel model proposed
- Dortmund (urban) path loss model
  Oulu [1]:
- Oulu Model

# North Denmark [3]:

- ▶ 3GPP Rural Macro non-line-of-sight (NLOS) model (rural areas)
- 3GPP Urban Macro NLOS model (urban areas)

- Additional parameters to increase the accuracy of path-loss predictions
- Soil condition, the climate, refraction and diffraction due to obstacles and terrain
- 20 MHz up to 20 GHz
- Widely used in the context of TV broadcasting

$$PL_{ITM} = PL_{fs} + A_{ref}$$

# Longley-Rice Irregular Terrain Model - SRTM

#### Resolution of 1 arc second ( $\approx$ 30 m) between 60°N and 57°S



# LoRa-Chipset





Chipset RSSI accuracy verification.

# **GPS-Chipset**

L76-L chipset

Geodetic measuring point: Deviation of 4 m





Fixed LoRa transceiver.

Moving LoRa transceiver.

# Acquisition of data

- Ten measurement points
- LoRa message size: 11 bytes
- Spreading factor: 12
- Coding rate: 4/5
- Bandwidth: 125 kHz
- 3,819 different measurements (Downlink)



# Acquisition of data

- Lost signals are included
- For multiple measurements on one location ( $10^{-3}$  decimal degrees  $\approx$  100m) we use the mean value to account different fading effects
- Measurements with no signal reception between two valid LoRa transmission are considered interference or collisions



### Location

The test was conducted at the Bonn-Rhein-Sieg University of Applied Sciences, Germany



Map of Sankt Augustin.



Free Space Path Loss prediction.



Oulu prediction.





#### False positive:

Signal reception predicted, no signal received

#### False negative:

No signal reception predicted, signal received

	ITM	FSPL	Oulu
False positive	12%	19%	5%
False negative	6%	0%	31%

Percentage share of false positives and false negatives.



Free Space Path Loss prediction.



Oulu prediction.



ITM prediction.

- No perfect model is apparent from a comparison of the results
- A model with a balanced ratio of false positives and false negatives could be the correct choice
- The ITM model generates this ratio and has the potential to significantly reduce this error at regions with huge elevation differences since especially mountains lead to many false negatives.
- It does not gratefully outperform other models for LPWAN but is especially useful in mountainous areas

# Future work

- Using LIDAR dataset the accuracy could be increased
- The state of North Rhine-Westphalia made a such a dataset (several terabyte) available online



# Are there any questions?

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