

An AI-driven Malfunction Detection Concept for NFV Instances in 5G*

Julian Ahrens

Mathias Strufe

Lia Ahrens

Hans D. Schotten

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Challenge: detect previously unencountered problems in VNFs using network and performance metrics

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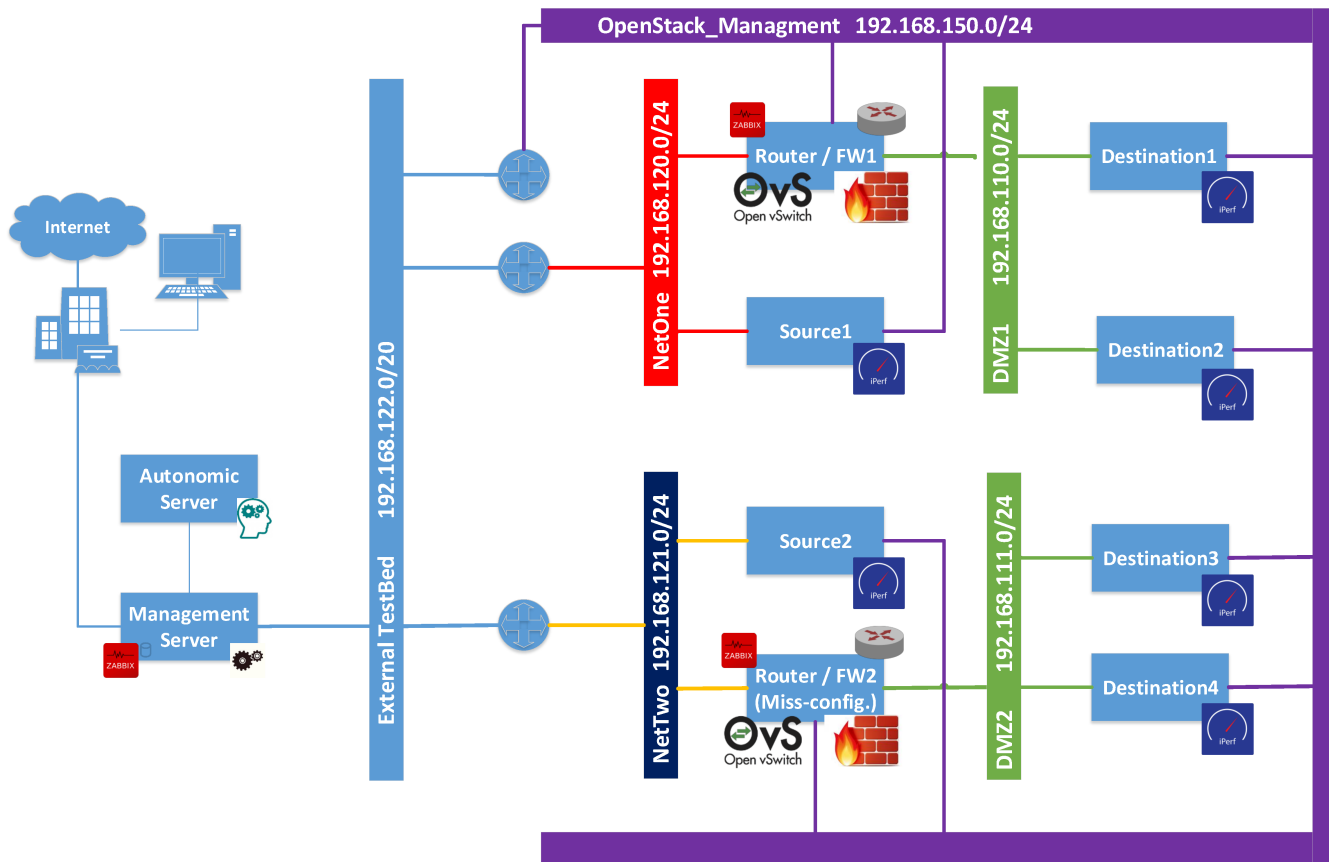
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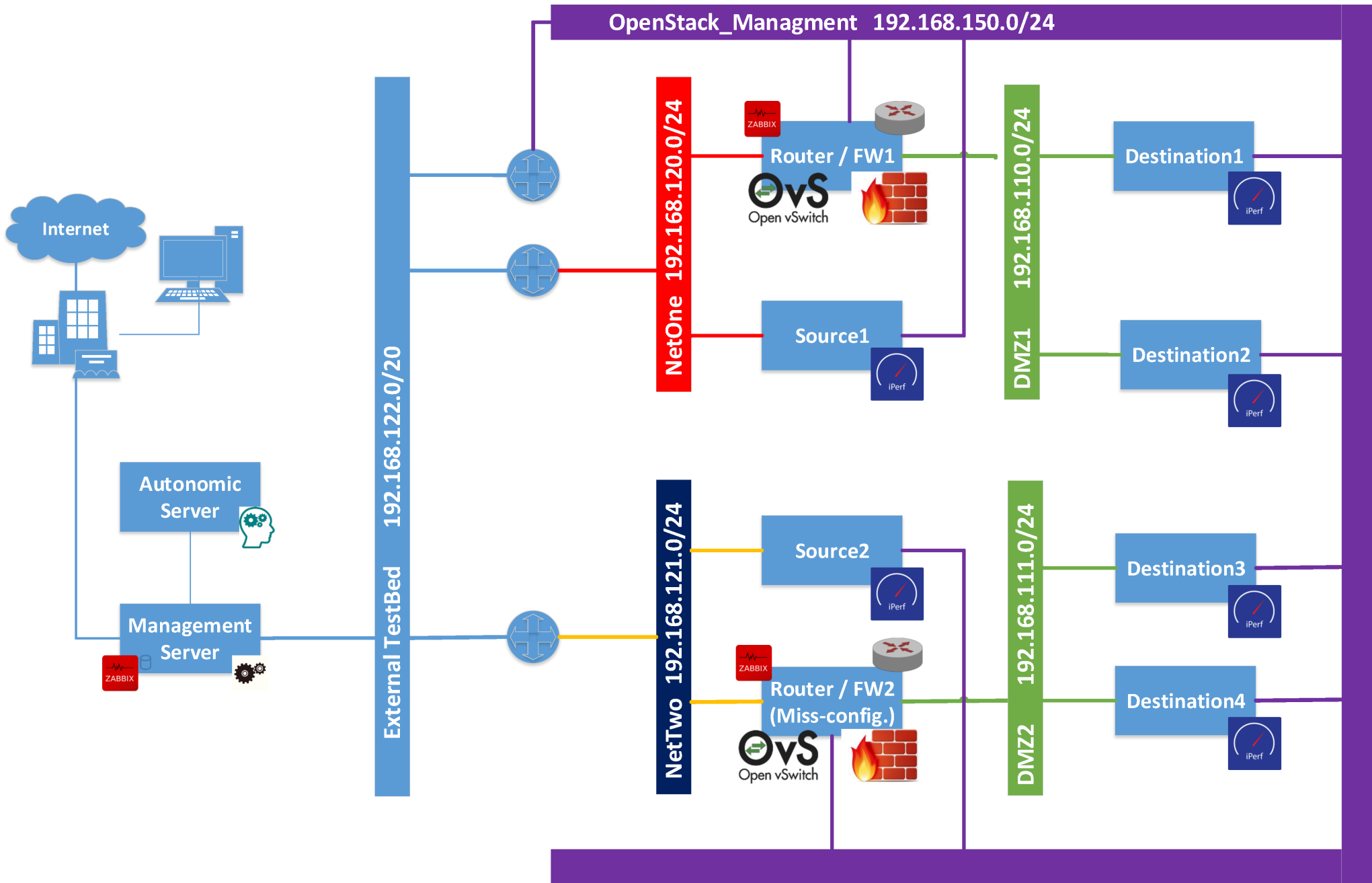
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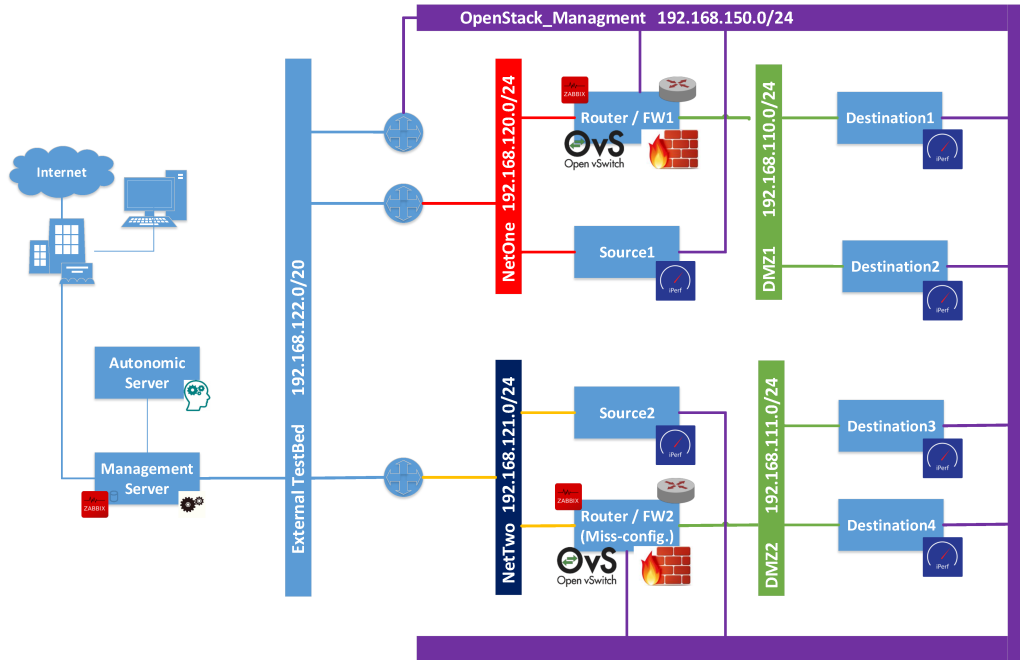
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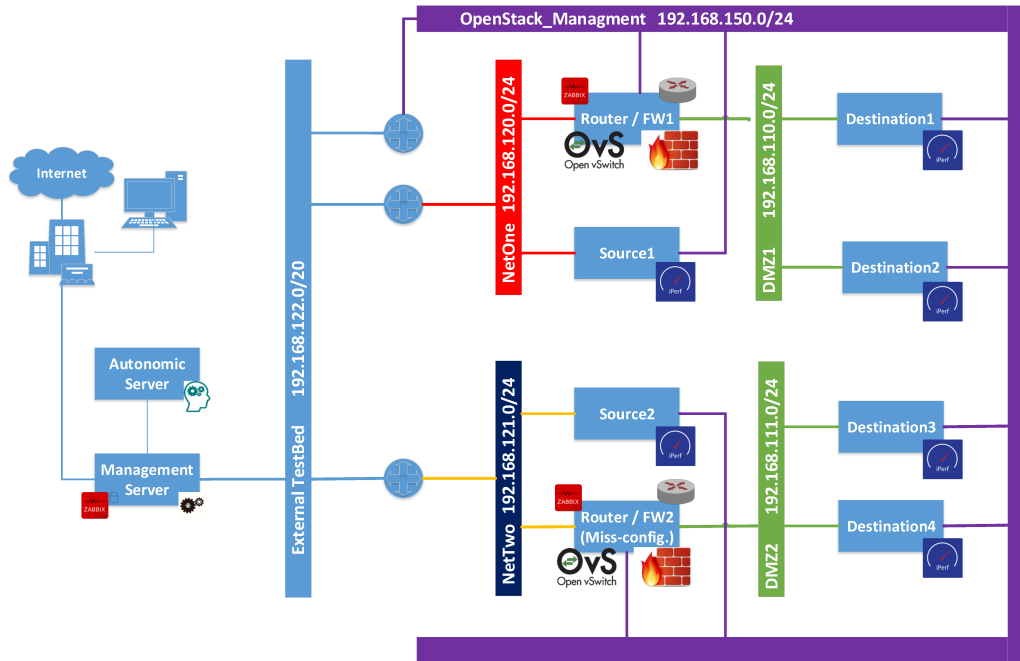
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- Example VNF: virtualized firewall

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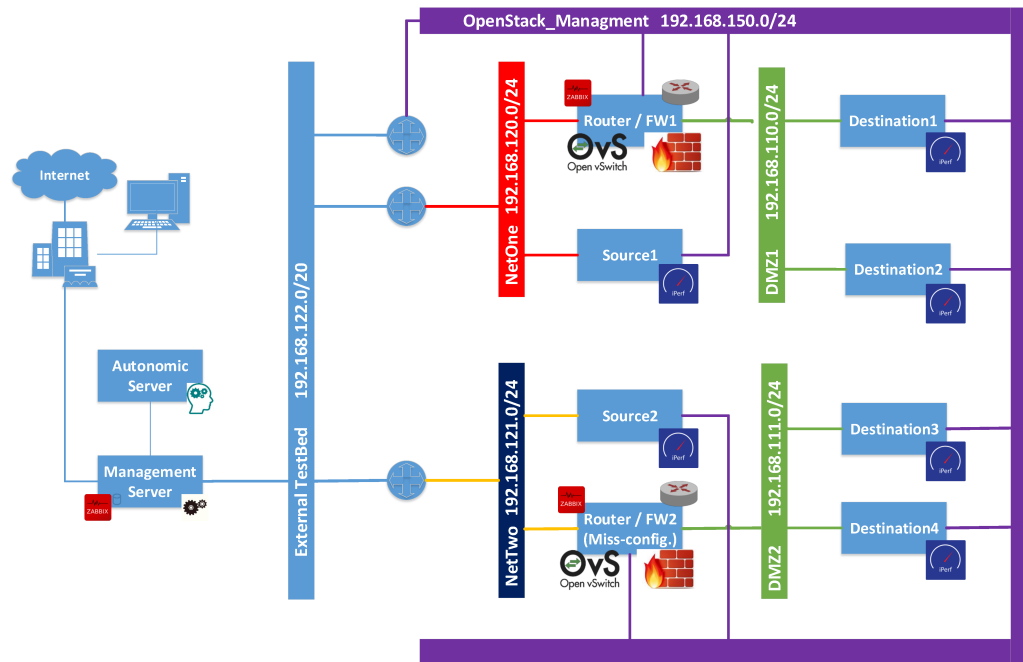
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- Example VNF: virtualized firewall
- Data flowing from the sources to the destinations

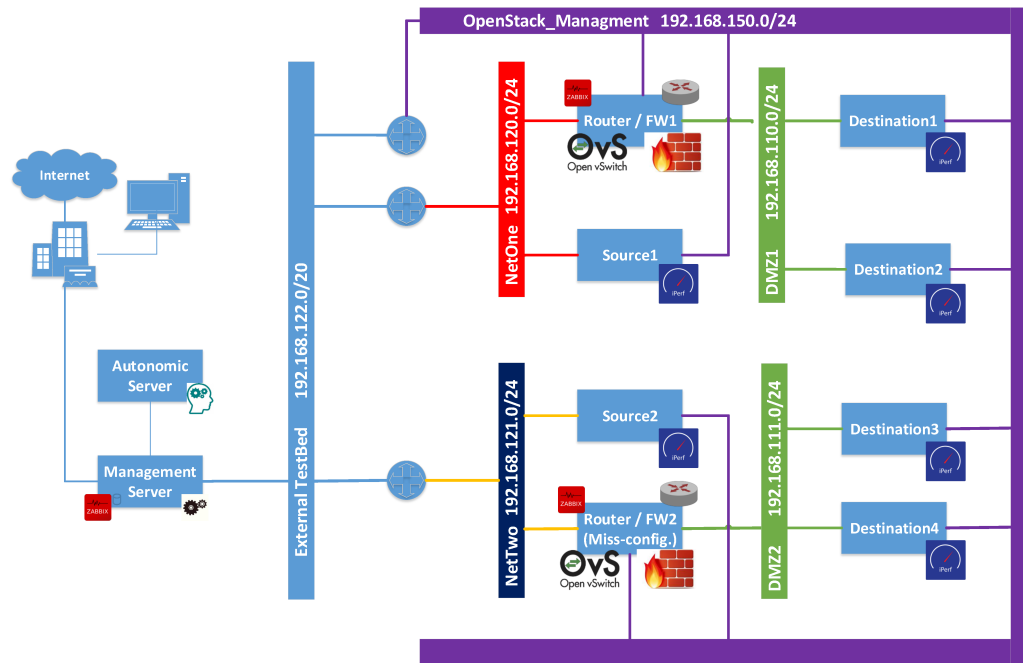
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- Example VNF: virtualized firewall
- Data flowing from the sources to the destinations
- Additional traffic between internet and destinations

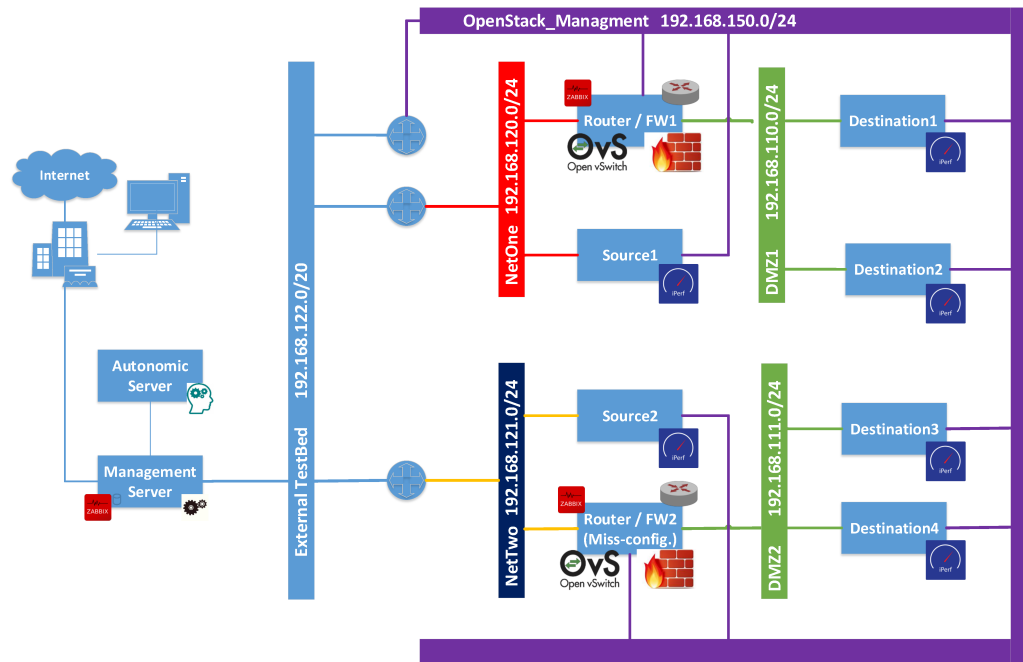
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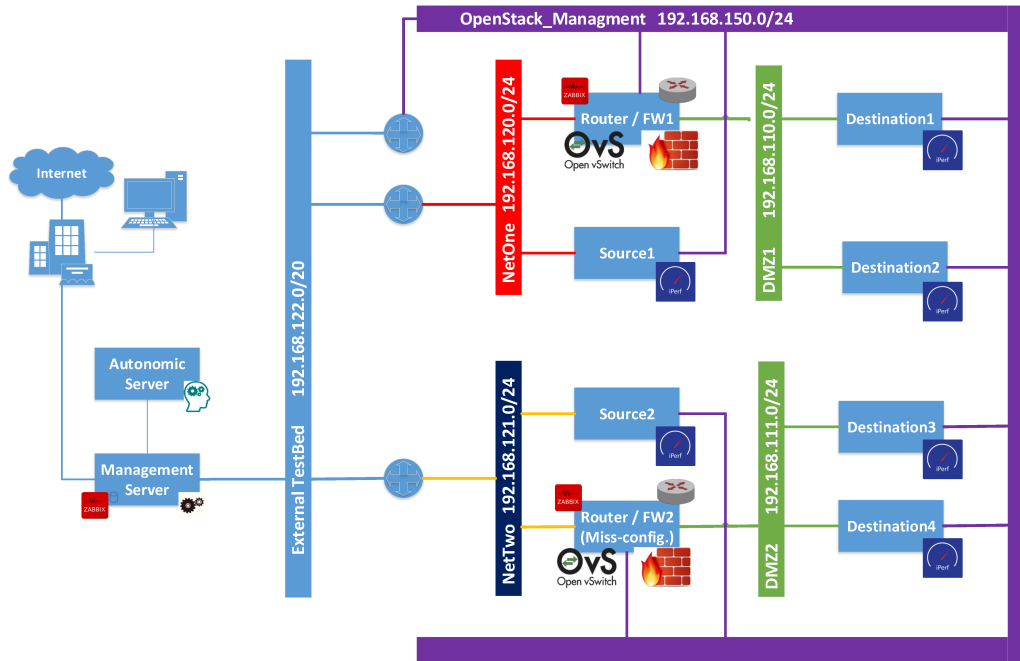
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- Example VNF: virtualized firewall
- Data flowing from the sources to the destinations
- Additional traffic between internet and destinations
- Firewalls filtering traffic from source to one of the destinations

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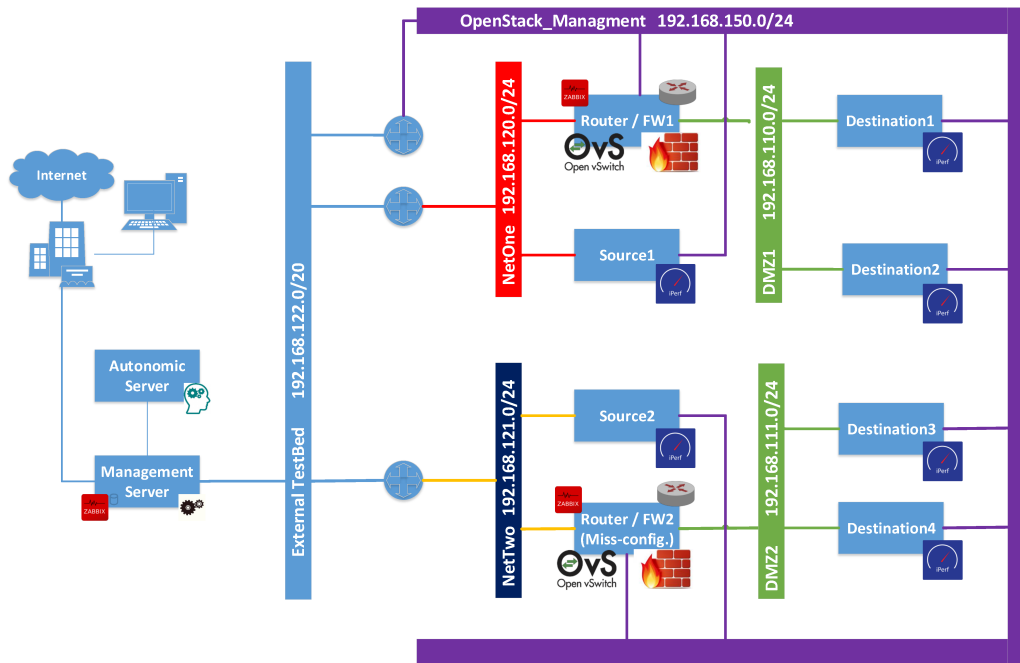
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- Features: CPU utilization, memory utilization, HDD utilization, network traffic in and out, each on two interfaces

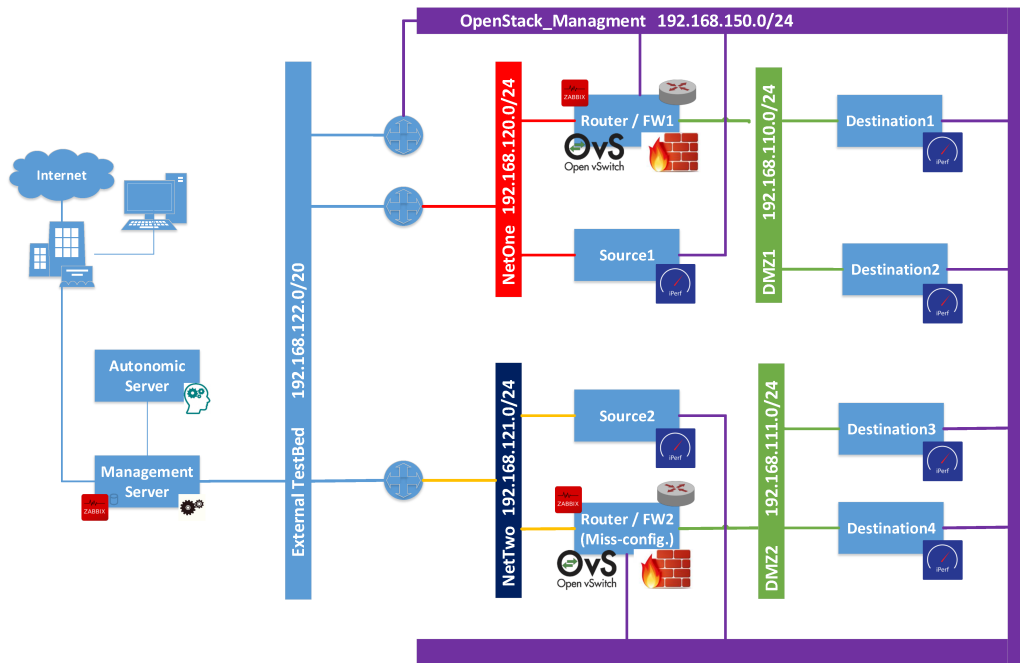
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- Features: CPU utilization, memory utilization, HDD utilization, network traffic in and out, each on two interfaces
→ seven features

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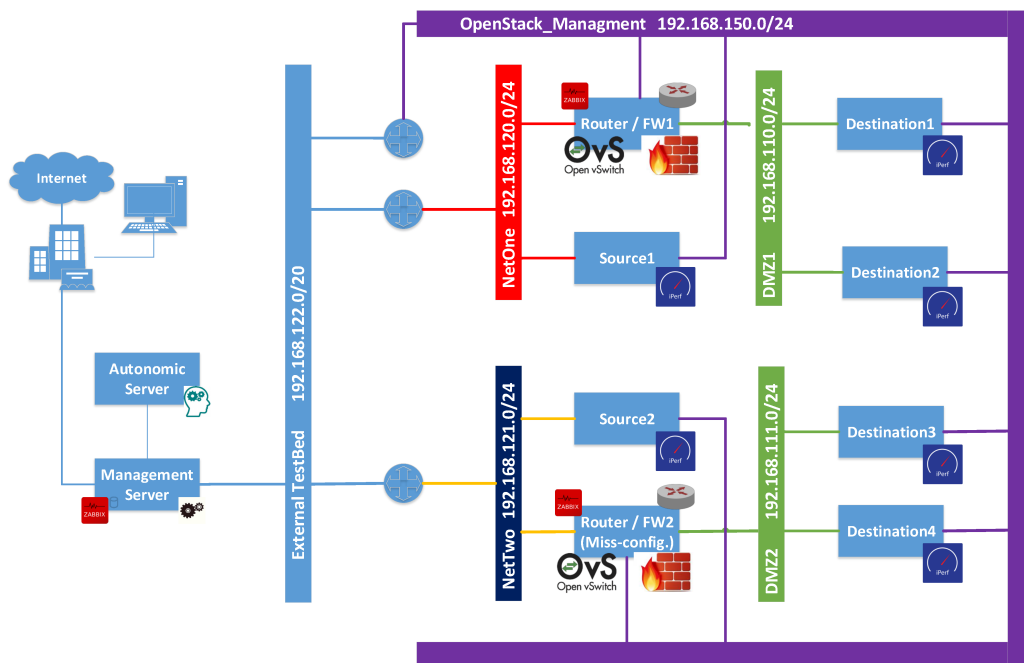
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- Features: CPU utilization, memory utilization, HDD utilization, network traffic in and out, each on two interfaces
→ seven features
- Anomaly used for testing: memory leak

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- Dataset of known good operation

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- Dataset of known good operation
- No actual anomalies are used during the training process

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- Dataset of known good operation
- No actual anomalies are used during the training process
- Available methods: clustering, dimensionality reduction / sparsity constraints

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- Dataset of known good operation
- No actual anomalies are used during the training process
- Available methods: clustering, dimensionality reduction / sparsity constraints
 - Measure of similarity required

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- Problem: Heterogeneity of data, multiple scales

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- Dataset of known good operation
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 - Normalization required

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- Dataset of known good operation
- No actual anomalies are used during the training process
- Available methods: clustering, dimensionality reduction / sparsity constraints
 - Measure of similarity required
- Problem: Heterogeneity of data, multiple scales
 - Normalization required
- Normalization via parametric and nonparametric statistical approaches

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- Dimensionality reduction via Autoencoders

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- Dimensionality reduction via Autoencoders
- Autoencoders are replicating artificial neural networks

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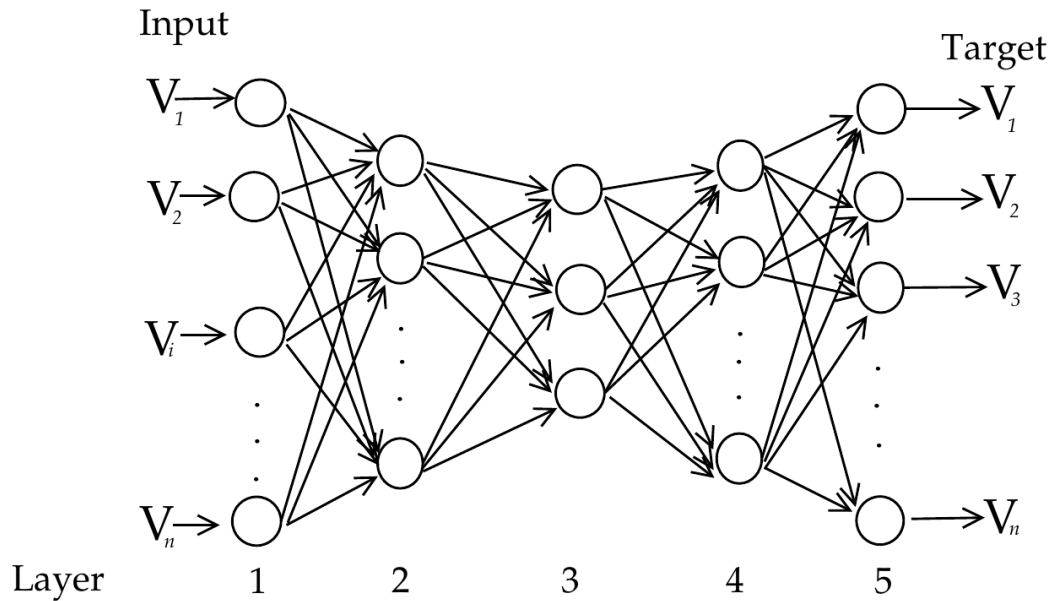
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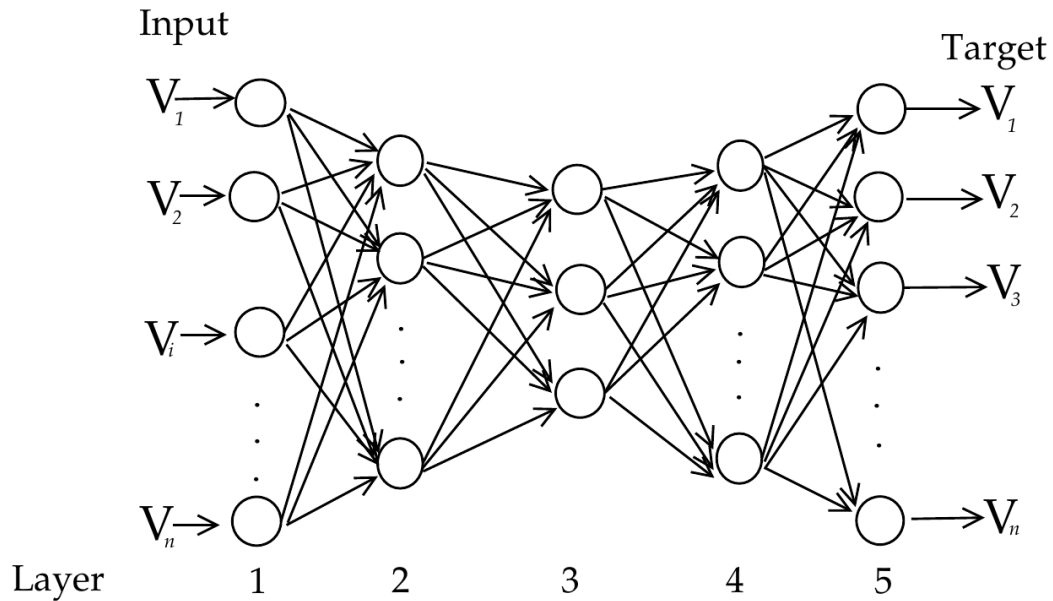
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- Both current value and difference to last value used as features

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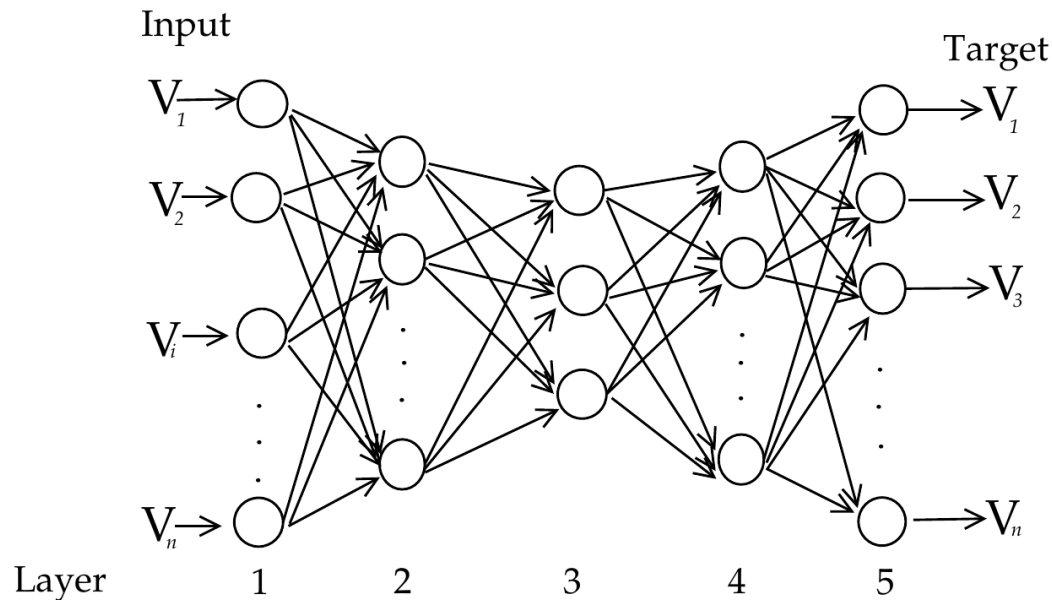
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- Both current value and difference to last value used as features
→ 14 features in the example setup

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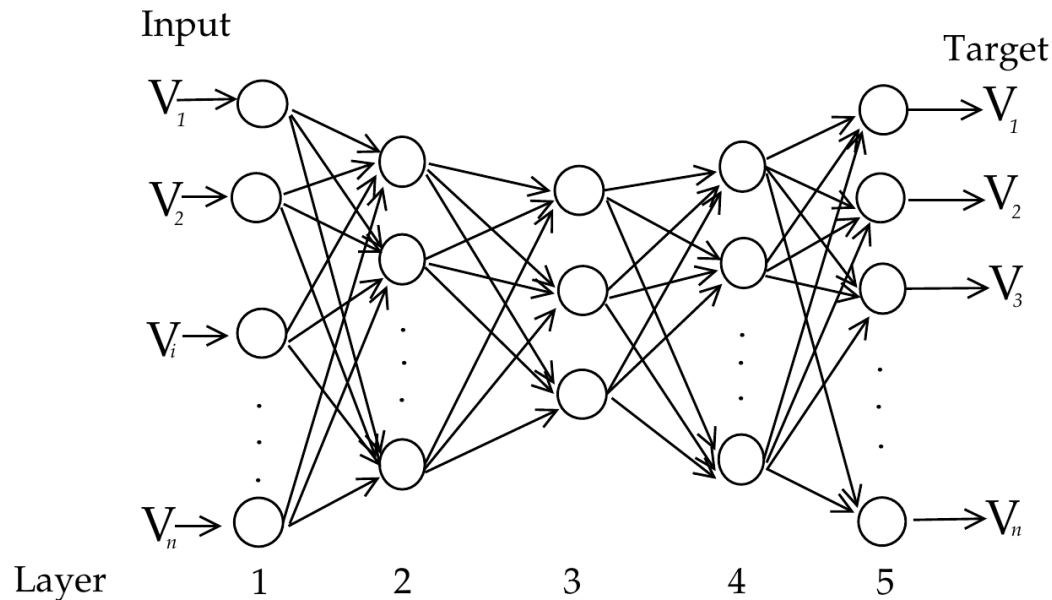
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- Dimensionality reduction via Autoencoders
- Autoencoders are replicating artificial neural networks



- Both current value and difference to last value used as features
→ 14 features in the example setup
- Hyperparameters: number of layers / layer sizes, activation function, learning rate during training

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- Measure of similarity: Euclidean distance

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- Measure of similarity: Euclidean distance
- Autoencoder is trained to best approximate its input by its output in the Euclidean distance over the training data

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- Measure of similarity: Euclidean distance
- Autoencoder is trained to best approximate its input by its output in the Euclidean distance over the training data
- Measure of normality: Euclidean distance of output of autoencoder to its input

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- If this distance is above a certain threshold, a datapoint is considered anomalous by the autoencoder

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- Hyperparameter: anomaly threshold

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- Measure of similarity: Euclidean distance
- Autoencoder is trained to best approximate its input by its output in the Euclidean distance over the training data
- Measure of normality: Euclidean distance of output of autoencoder to its input
- If this distance is above a certain threshold, a datapoint is considered anomalous by the autoencoder
- Hyperparameter: anomaly threshold
- Use an additional validation dataset to adjust the anomaly threshold until the number of false positives reaches a desirable level

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- Use more than one autoencoder in order to capture different characteristics of the data

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- Use more than one autoencoder in order to capture different characteristics of the data
- Different autoencoders governed by different hyperparameters

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- Use more than one autoencoder in order to capture different characteristics of the data
- Different autoencoders governed by different hyperparameters
- Allows for diversity in sparsity, nonlinearity, etc.

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- Use more than one autoencoder in order to capture different characteristics of the data
- Different autoencoders governed by different hyperparameters
- Allows for diversity in sparsity, nonlinearity, etc.
- In the test scenario: three to seven layers, central layer sizes from two to eight neurons, tanh and ReLU activation functions, total of 216 autoencoders

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- Use more than one autoencoder in order to capture different characteristics of the data
- Different autoencoders governed by different hyperparameters
- Allows for diversity in sparsity, nonlinearity, etc.
- In the test scenario: three to seven layers, central layer sizes from two to eight neurons, tanh and ReLU activation functions, total of 216 autoencoders
- Vote among autoencoders: a datapoint is considered normal if enough of the autoencoders consider the datapoint normal; otherwise, it is considered anomalous

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- Significant generalization performance

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- Significant generalization performance
- Most of the autoencoders converge very well on the validation dataset

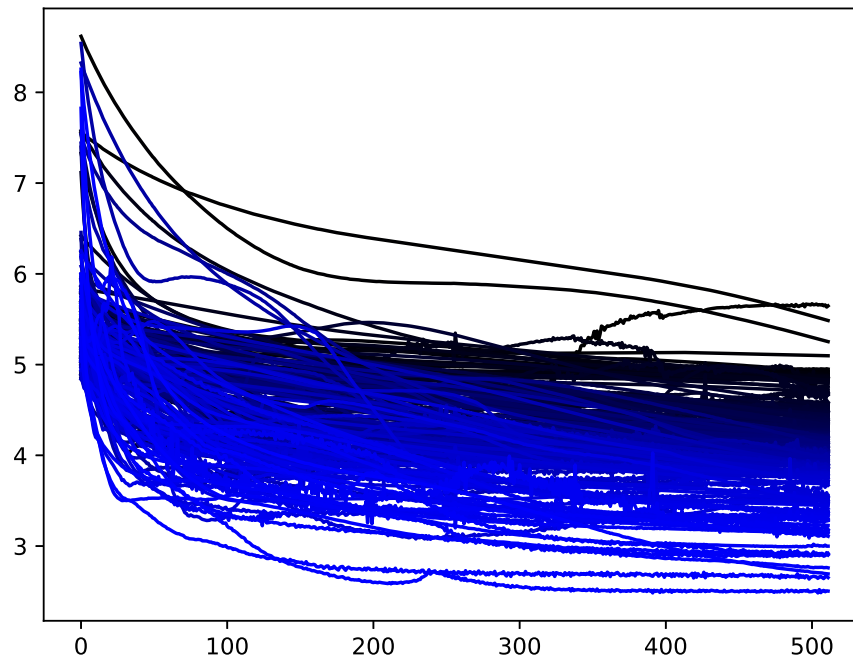
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- Significant generalization performance
- Most of the autoencoders converge very well on the validation dataset



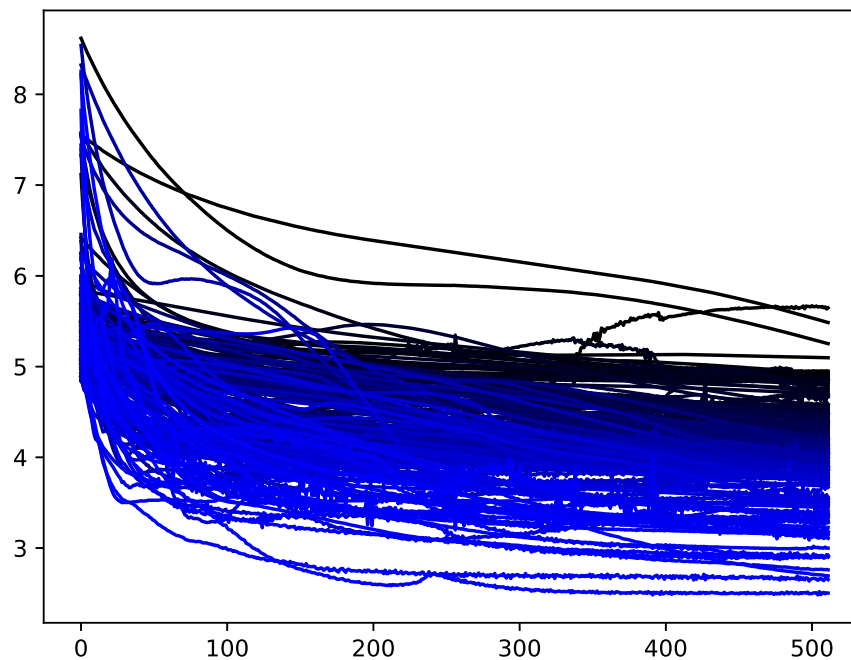
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- Significant generalization performance
- Most of the autoencoders converge very well on the validation dataset



- 80.4% detection rate vs. 0.7% false positives

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Questions?

Thank you!