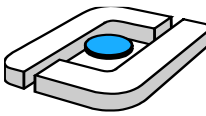


Monitoring and Testing for Reliable Smart City Applications

21. VDE/ITG Fachtagung Mobilkommunikation
Osnabrück, 12.05.2016

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Introduction

- CityPulse Framework

Reliable Smart City Application

- Travel Planner

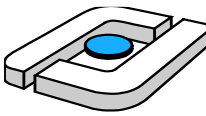
Testing Concept

Monitoring Concept

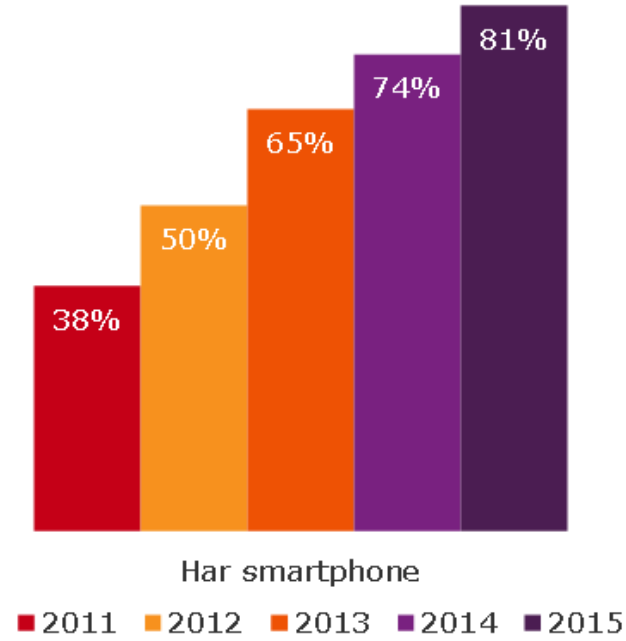
- Atomic Monitoring
- Composite Monitoring

Conclusion





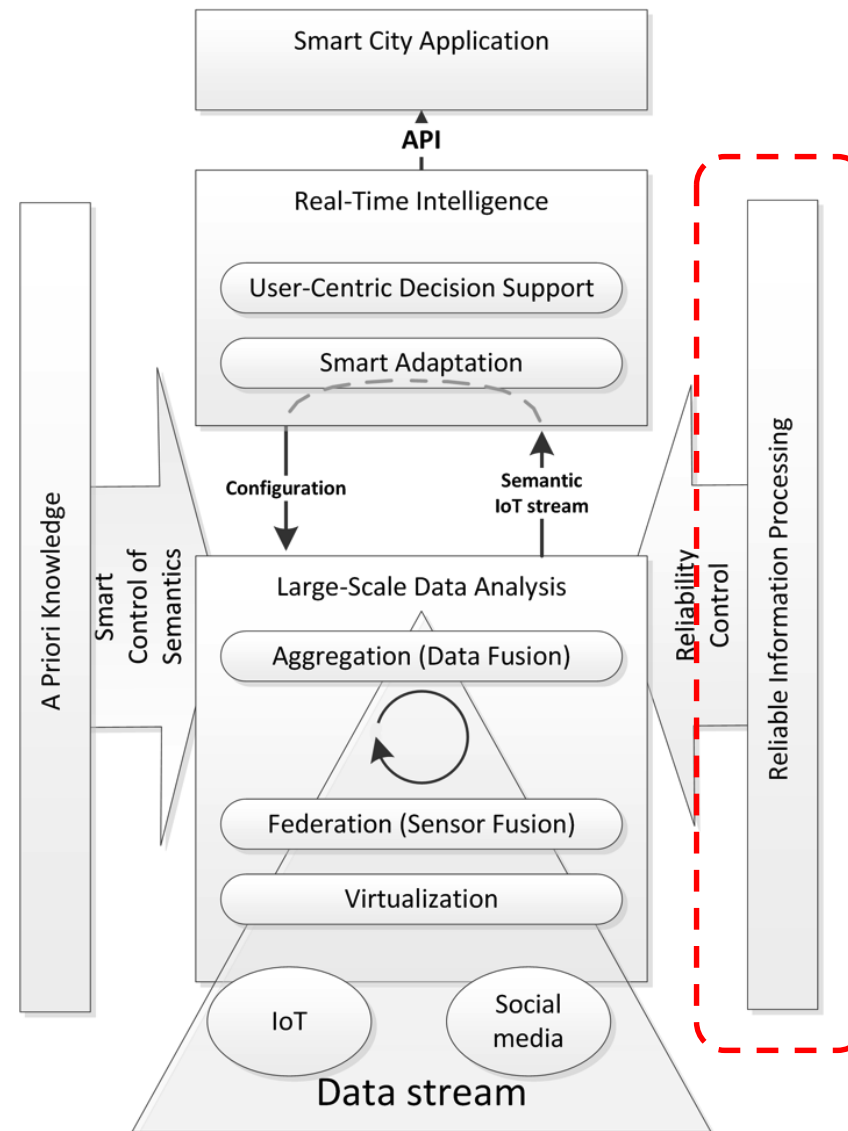
- ❑ Smartphone distribution increasing
- ❑ Germany > 50%
- ❑ Denmark:

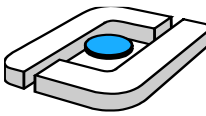


- ❑ New applications to enhance life of citizens
 - Simple (weather or pollution forecasts), Complex (shopping planner with integrated user preferences, e.g. “avoid pollution”, “use scenic routes”)

Architecture of CP-Framework

- Virtualisation
- Federation (Sensor Fusion)
- Aggregation (Data Fusion)
- Smart Adaptation
- User Centric Decision Support
- Reliable Information Processing
- Smart City Applications





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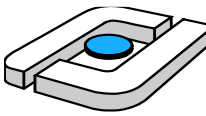
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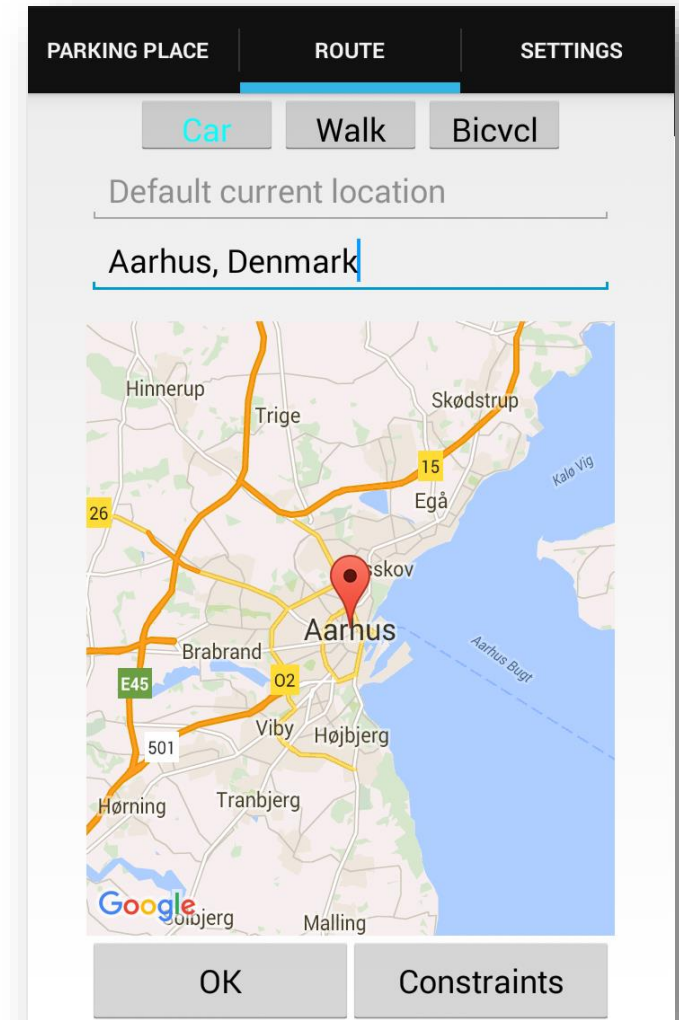


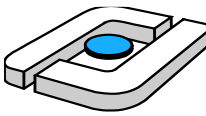
❑ Travel Planner application

- Asks user for destination in Aarhus, selects near parking garage with free parking slots
- Contains features to constrain routing process by user preferences
- On the fly route changes if events detected by CP-framework
- Highly depended on used data sources
 - CP-QoI-Monitoring components allow real-time Quality Monitoring for data streams
 - Data sources annotated with semantic annotation, allows reasoning and conflict resolution

❑ Prone to faulty data delivered by used data streams

- Faulty data requires complex application testing before deployment
- Applications may require certain QoI levels
- Testing of applications with degenerated data streams will result in minimum QoI requirements for applications





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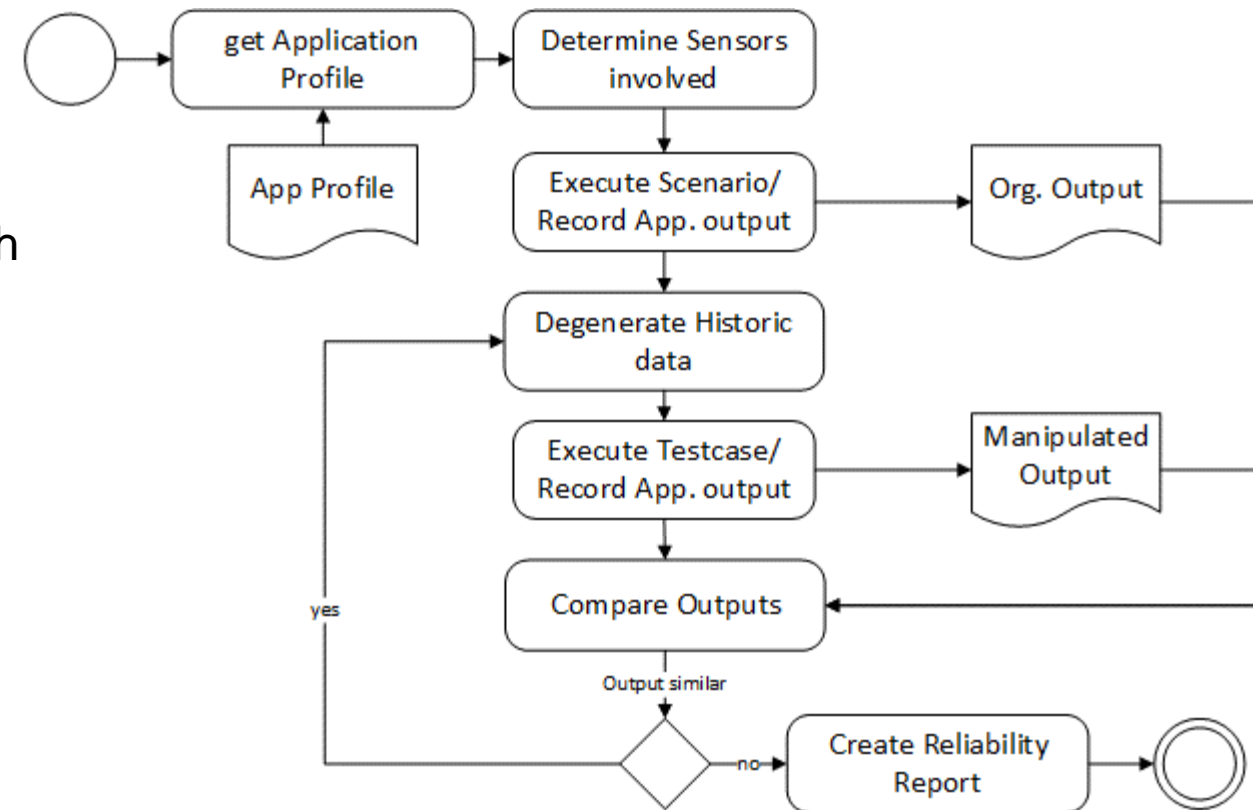
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Conclusion



- ❑ Goal: evaluate reliability of smart city applications
- ❑ Problem: no ground truth for datasets available
 - Collected data for December 2015 used as reference dataset
- ❑ Approach:
 - Determination of required data streams/sensors
 - First testcase T_0
 - Output of CP-framework used as ground truth
 - Testcase T_n
 - Degeneration of input data
 - Output compared to output of further tests
 - Passed if distance between T_n and T_{n-1} is below a threshold



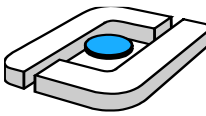
□ Generation of test case stimuli:

1. **While** $\tau = A + (r * \text{tick}) < \Omega$:
2. **For** each sensor s in S :
3. $v = H(s, \tau)$
4. **For** each error e in E :
5. **If** ($P_{e,s} = \text{true}$ **and** e not active)
6. activate e
7. $v' +=$ apply e on v if e is active

□ v' substitutes historic values in H to form a new testcase

□ Process is repeated n times

○ Set of testcases with decreasing (more unreliable) stream data



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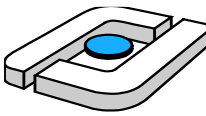
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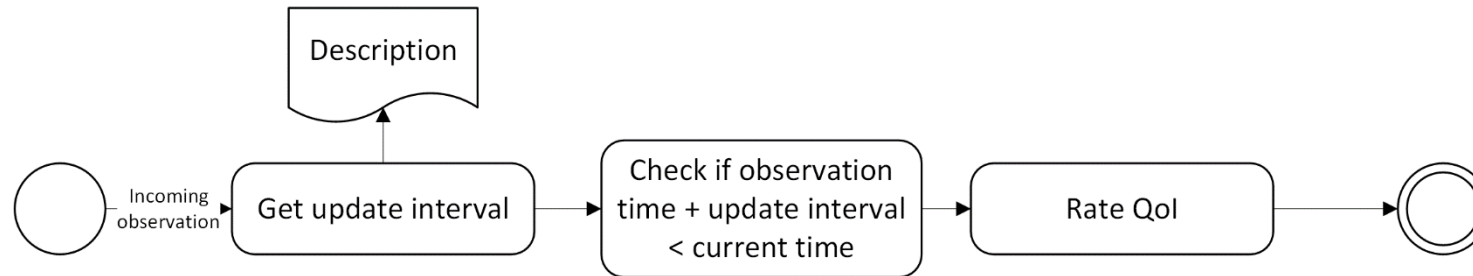




- ❑ Smart city applications depend on
 - appropriate,
 - accurate,
 - trustworthy
 - ... data streams
- ❑ Data stream reliability has to be monitored in real-time
- ❑ Monitoring methods compare data stream QoI with required QoI level for application
- ❑ To fulfil real-time requirements CP-Monitoring is split into two components
 - Atomic Monitoring
 - Rudimentary QoI check for single data streams
 - Real-time sanity checks
 - Composite Monitoring
 - Validation of detected events by investigating correlation between spatial-correlated streams
 - Computationally complex

- ❑ Real-time QoI annotation of incoming sensor observation from data streams
- ❑ Directly integrated into Data Wrapper of stream
- ❑ Includes only basic QoI checks based on a stream description

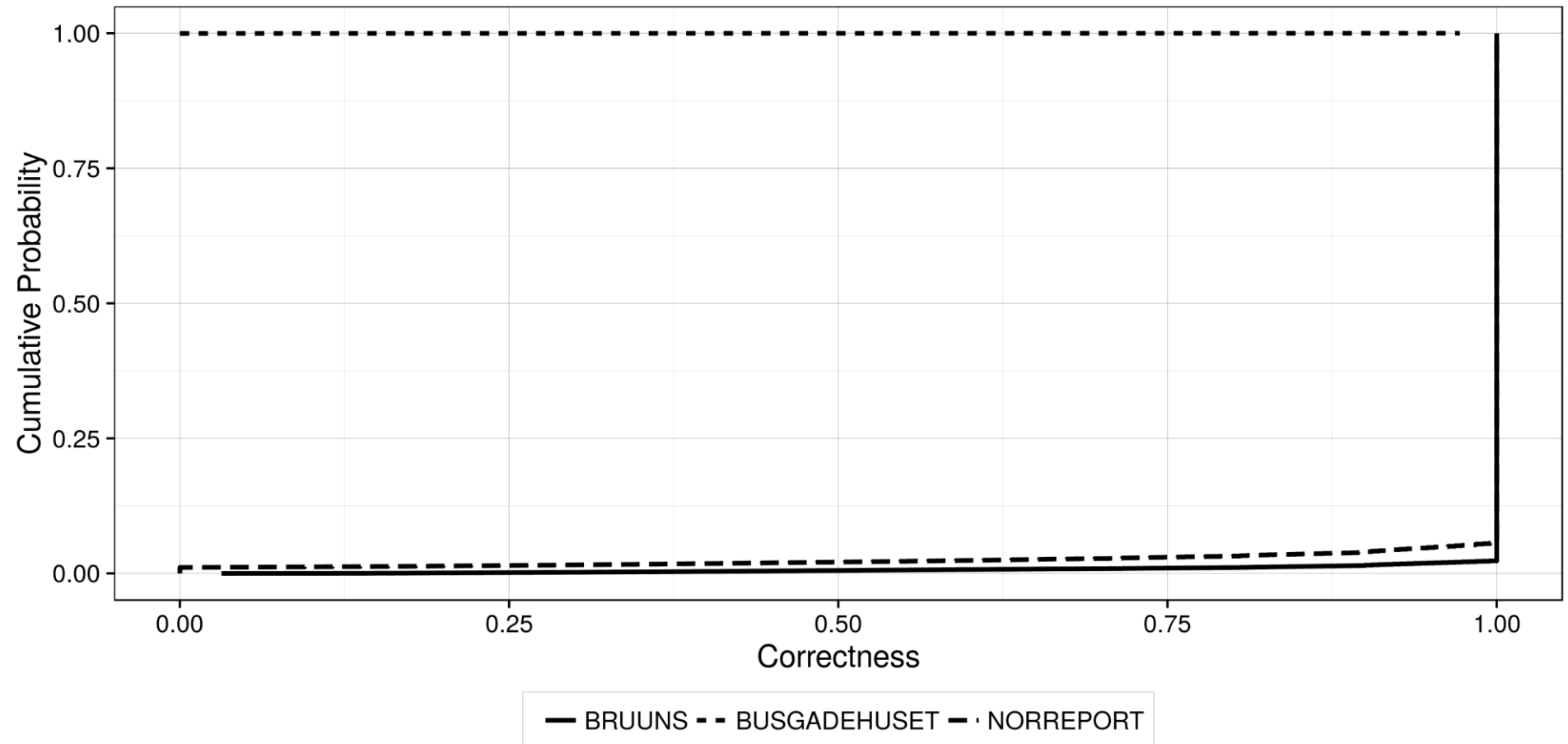
- Age

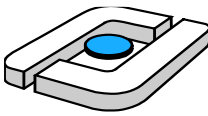


- Completeness
- Correctness
- Frequency
- Latency

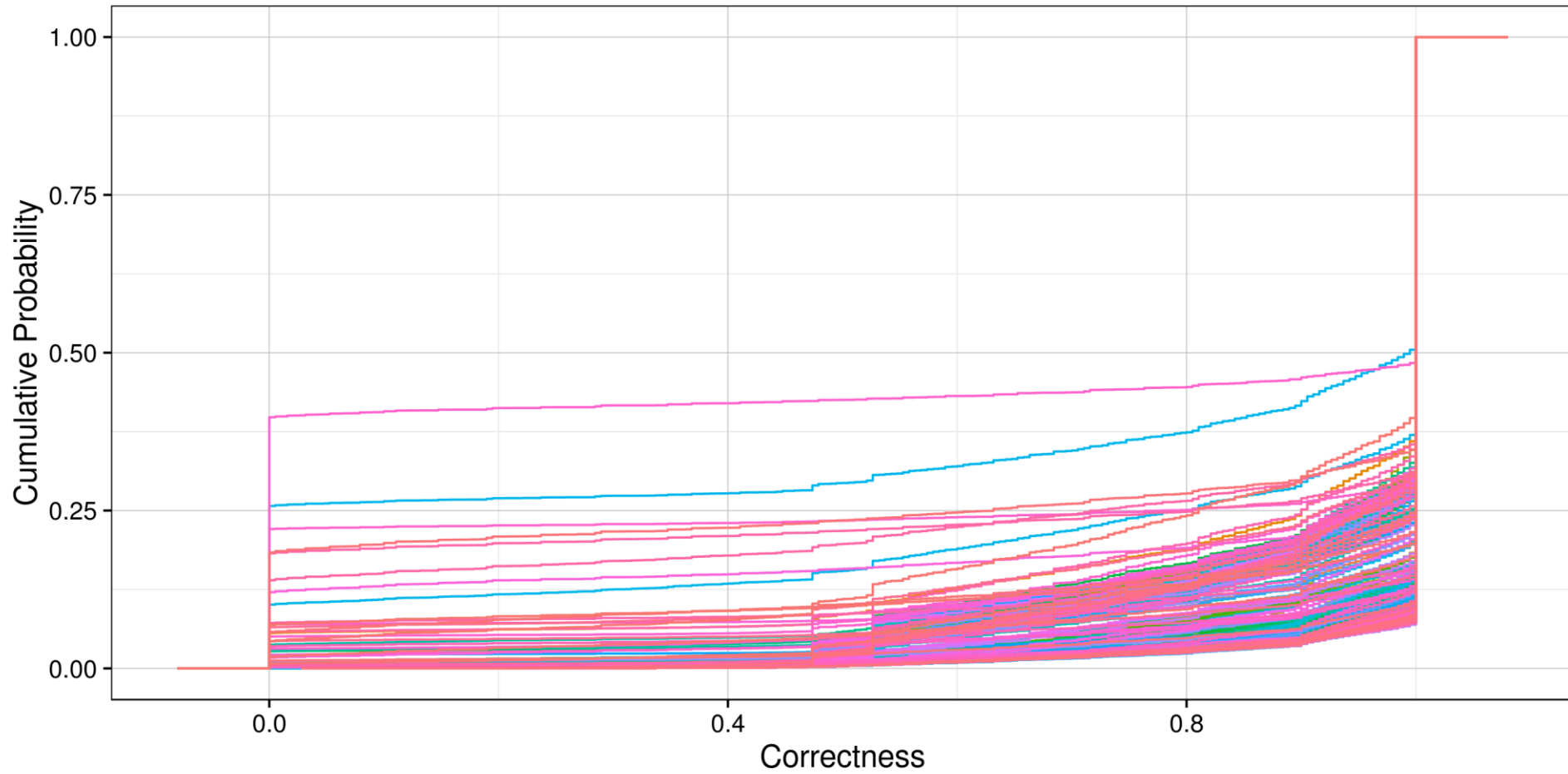
□ Results

- Experiments done with Parking and Traffic data stream for Aarhus (December 2015)
- Parking



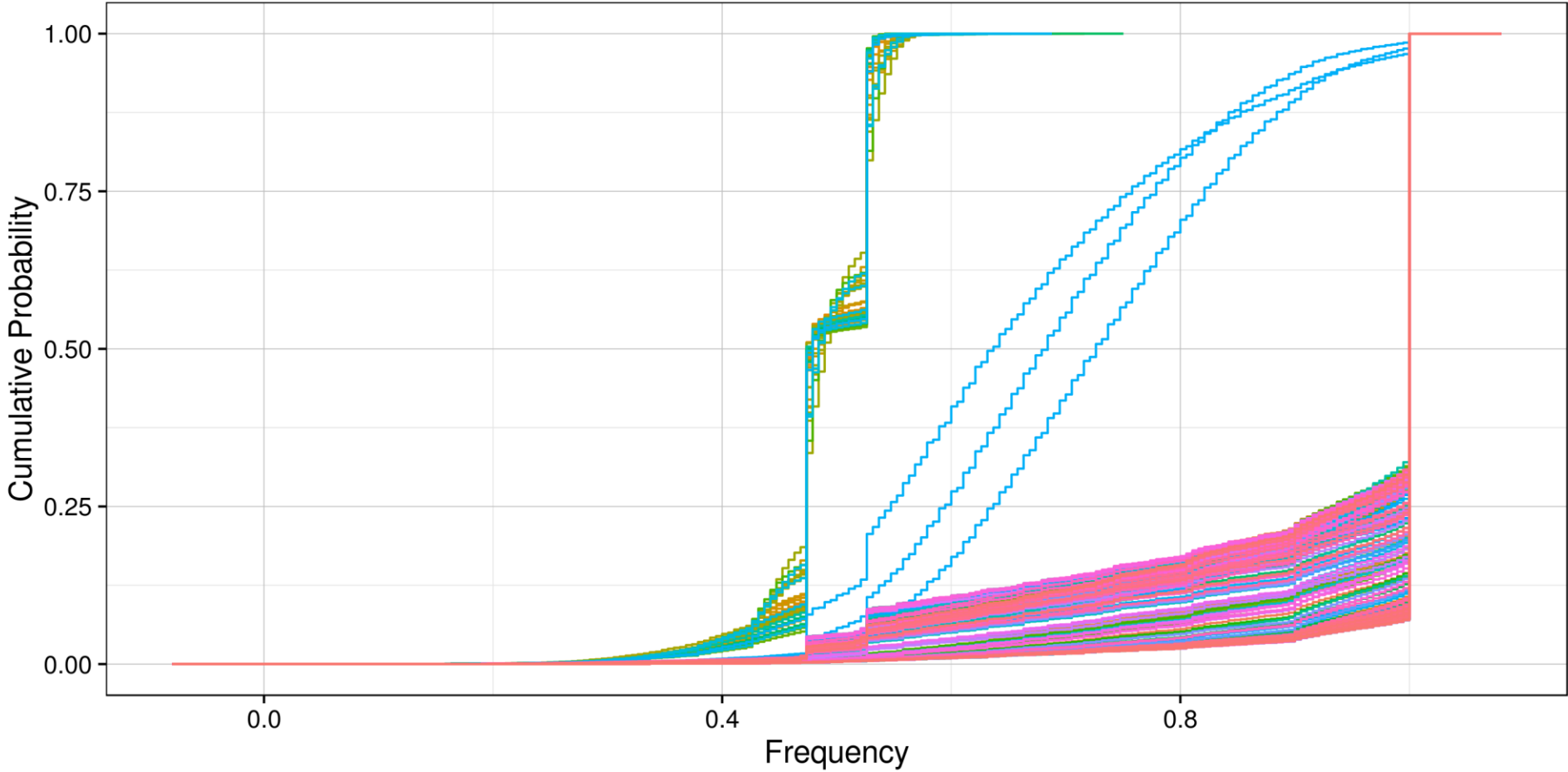


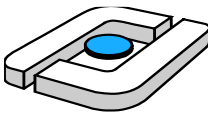
❑ Traffic Correctness



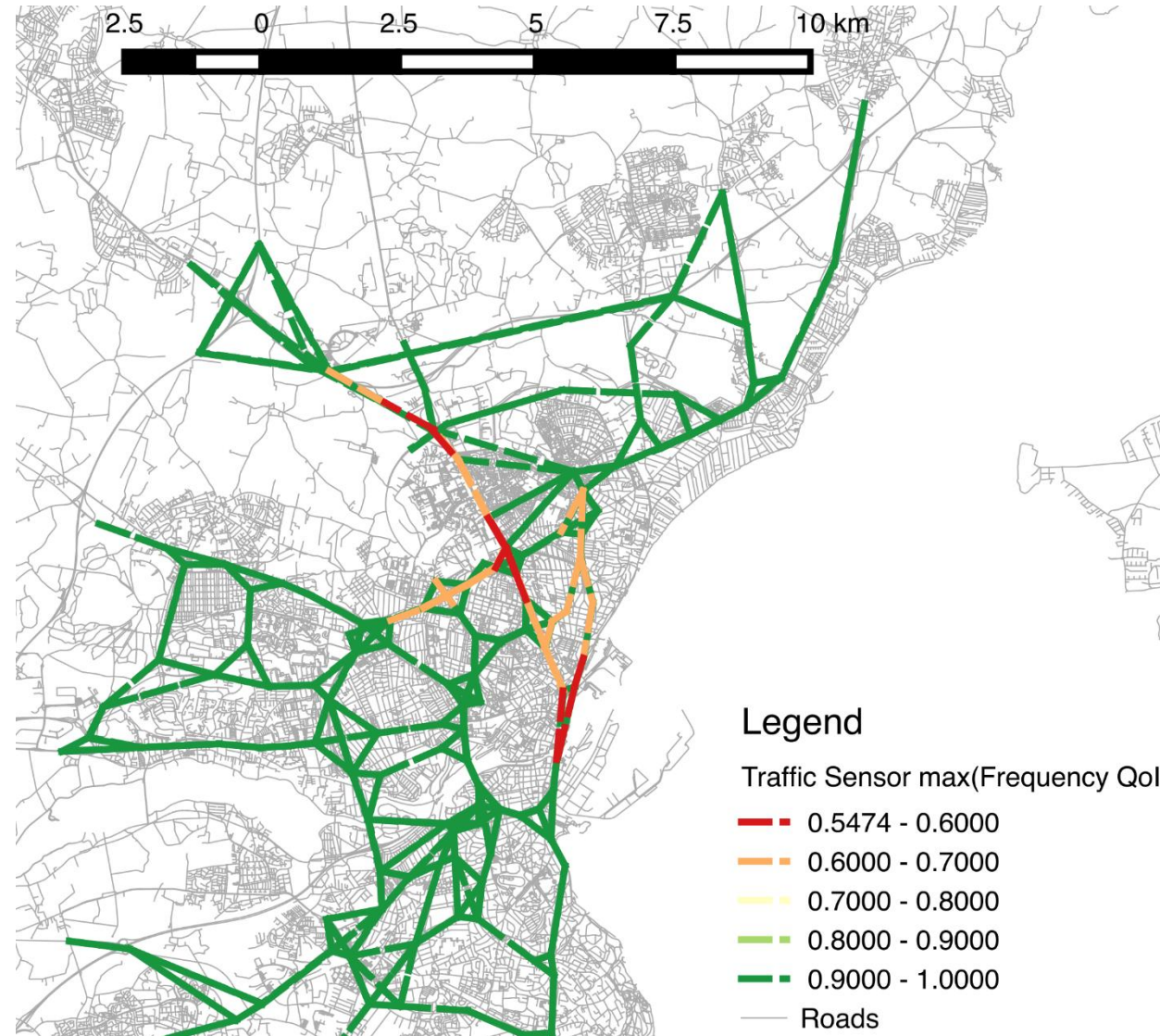


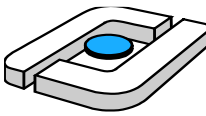
❑ Traffic Frequency





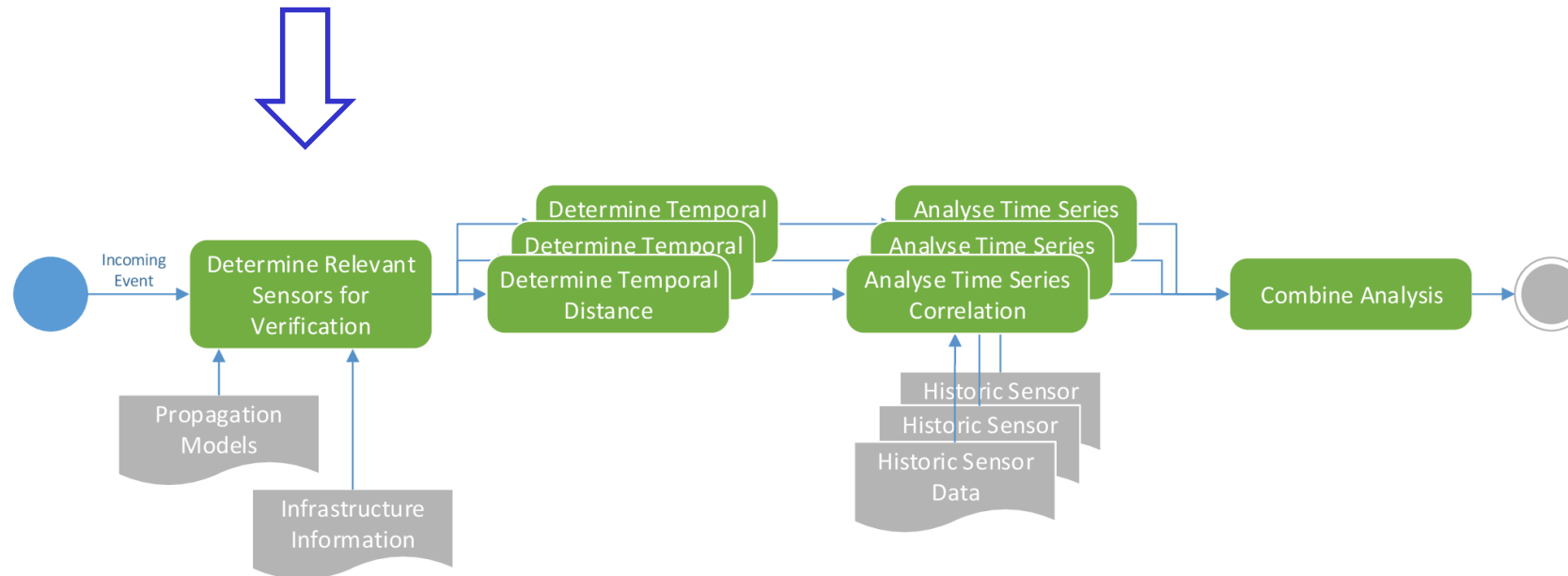
□ Traffic Frequency



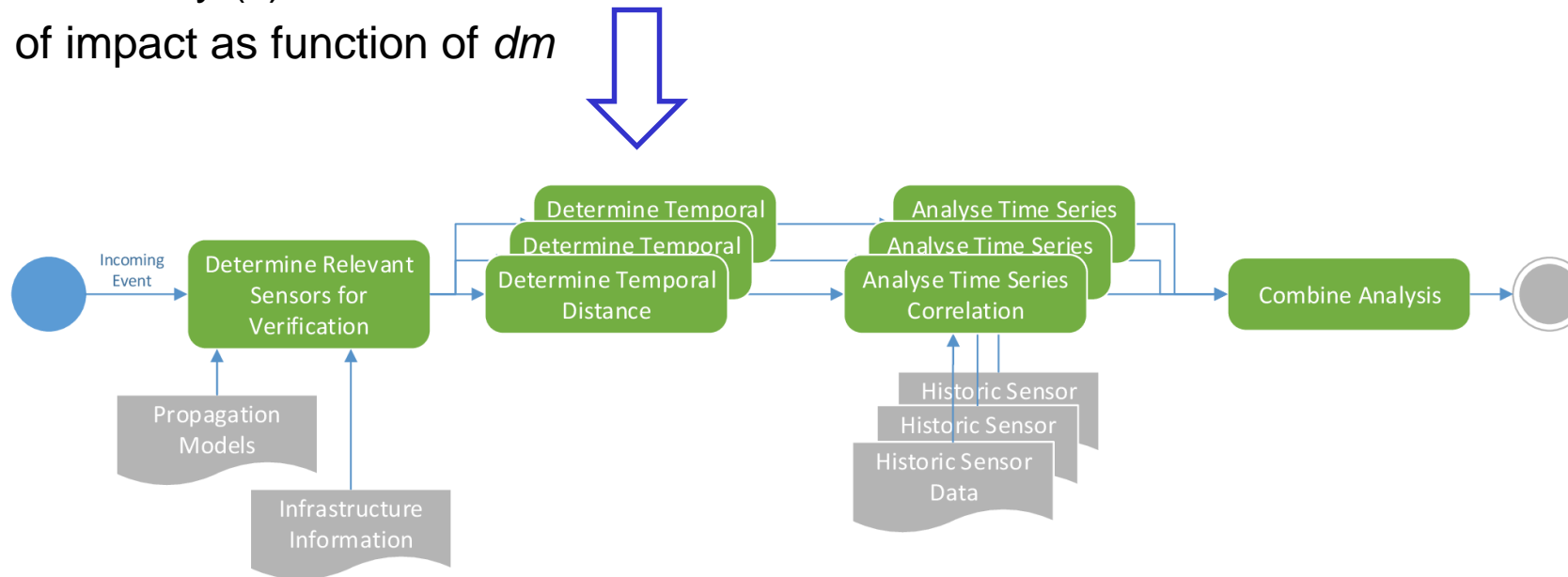


- ❑ Main objective: prediction of errors and plausibility of events
- ❑ Main challenge: no available ground truth
- ❑ Composite Monitoring
 - Model based analysis of tempo-spatial related stream/sensor data
 - E.g. traffic sensor
 - A sensor reports slow traffic → results in a detected traffic jam
 - Composite Monitoring validates event with the use of consecutive sensors on road
 - Usage of historic data (Atomic uses only current data of one sensor)
 - No real-time capabilities
 - Triggered by events or manual evaluations

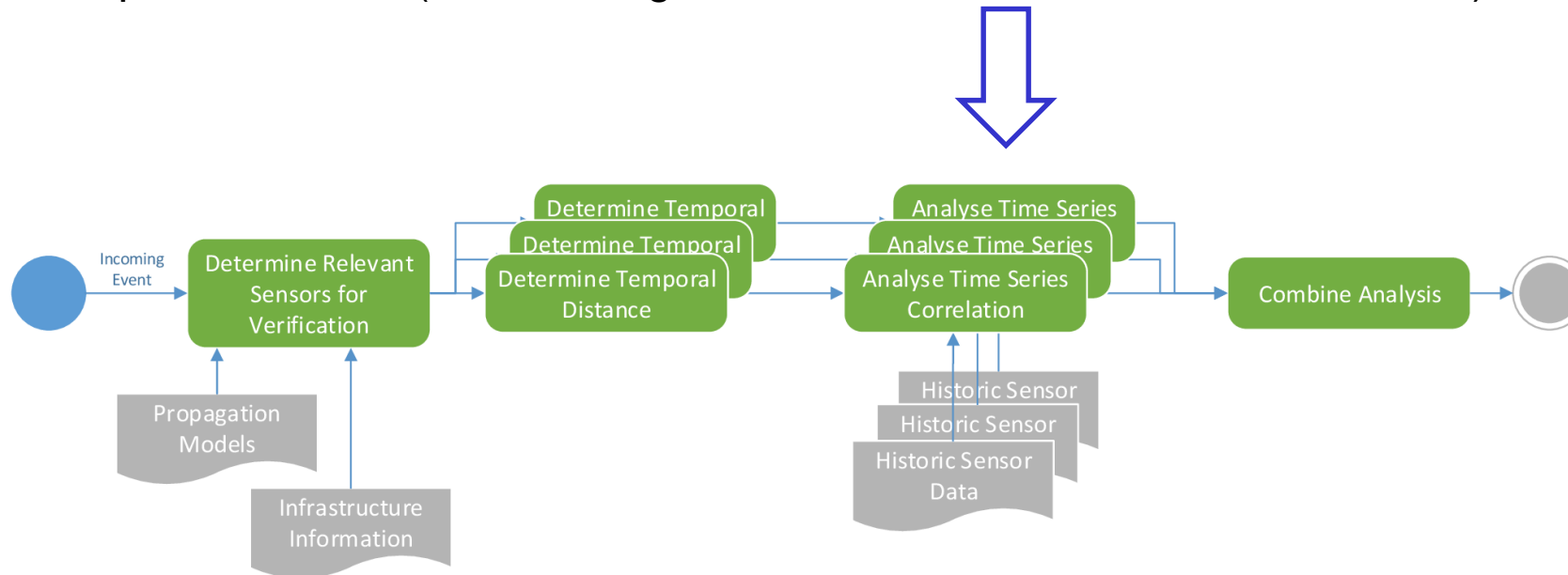
- ❑ Determine relevant sensors out of the set of all Streams (s)
 - Find spatially correlated streams by using a suitable distance model (dm), which describes the means of propagation of the event (air/street)



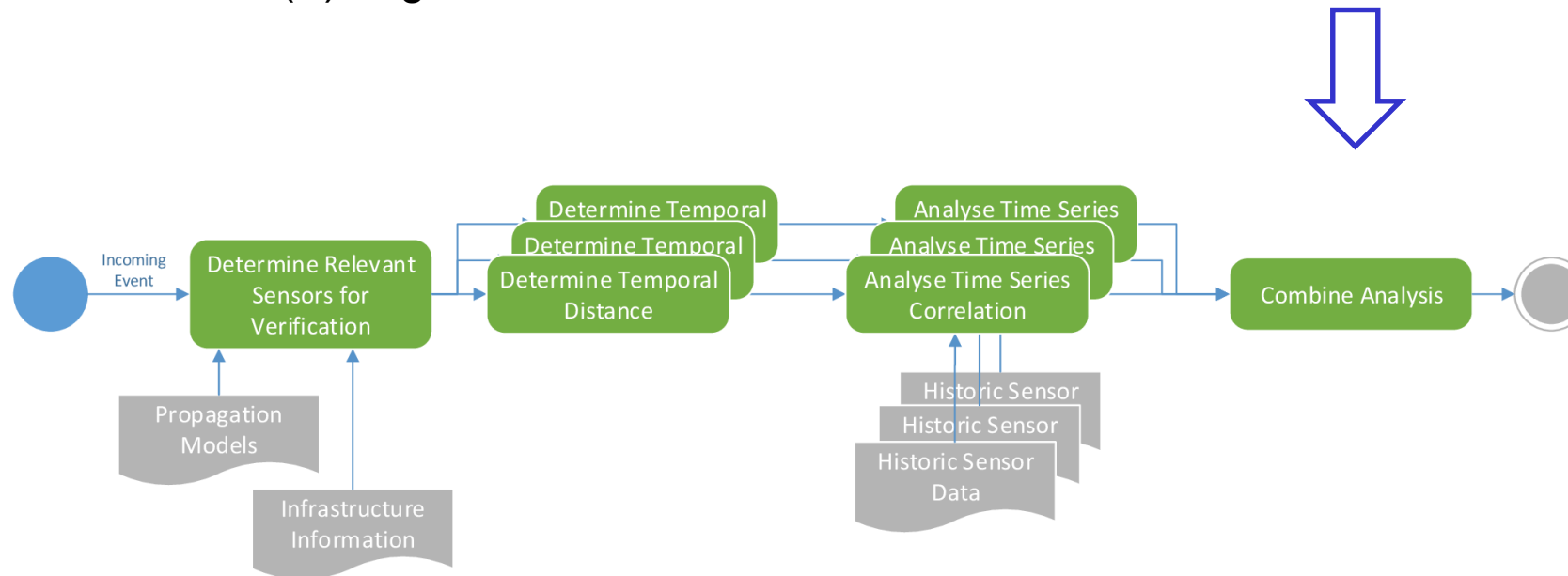
- ❑ Determine temporal distance by analysing the
 - Direction (d) of expansion
 - Propagation velocity (v)
 - Range (r) of impact as function of dm



- Compute the correctness for each correlated stream by applying
 - V_s as the set of validator functions for e and each stream $s \in S_e$
 - τ_s as set of temporal direction (is the change in s a result of e , or is it a cause for e ?)



- Combine all partial correctness values by using the:
 - Set of weights (Ws) for each stream $s \in Se$
 - A combination function (Σ), e.g. min, mean



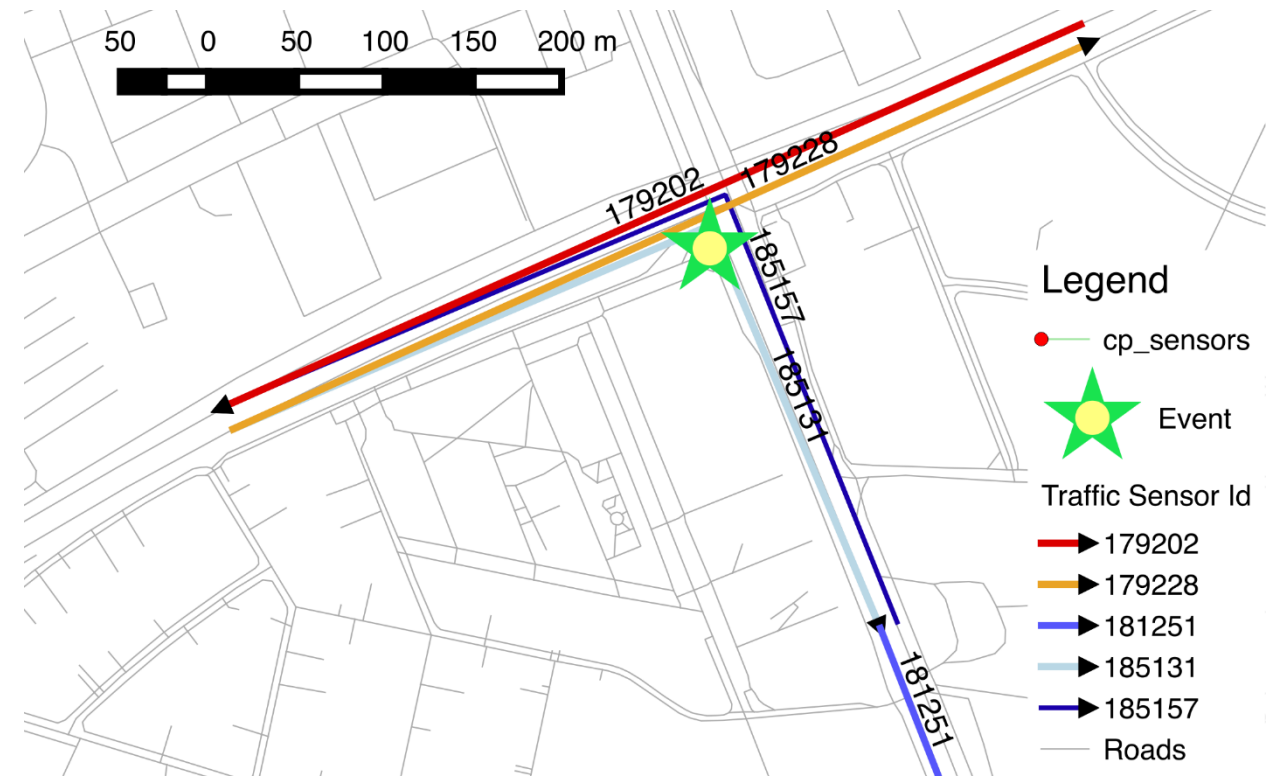
- As a result, we get the combined correctness value (C_e)
 - $C_e = (S, dm, d, v, r, Vs, \tau_s, Ws, \Sigma)$.

- ❑ Example: Traffic Jam event created by Event Detection
 - Detected by sensors
 - Composite Monitoring is triggered by the event

```
sao:a26db0a4-20ca-4f4c-b553-a799200d58ca a
ec:TrafficJam ;
    ec:hasSource "SENSOR";
    sao:hasLevel "1"^^xsd:long;
    sao:hasLocation [ a geo:Instant;
        geo:lat "56.18244908701999"^^xsd:double;
        geo:lon "10.1972915214958"^^xsd:double
    ] ;
    sao:hasType ec:TransportationEvent ;
    tl:time "2016-02-12T13:57:07.001Z"^^xsd:dateTime
.
```

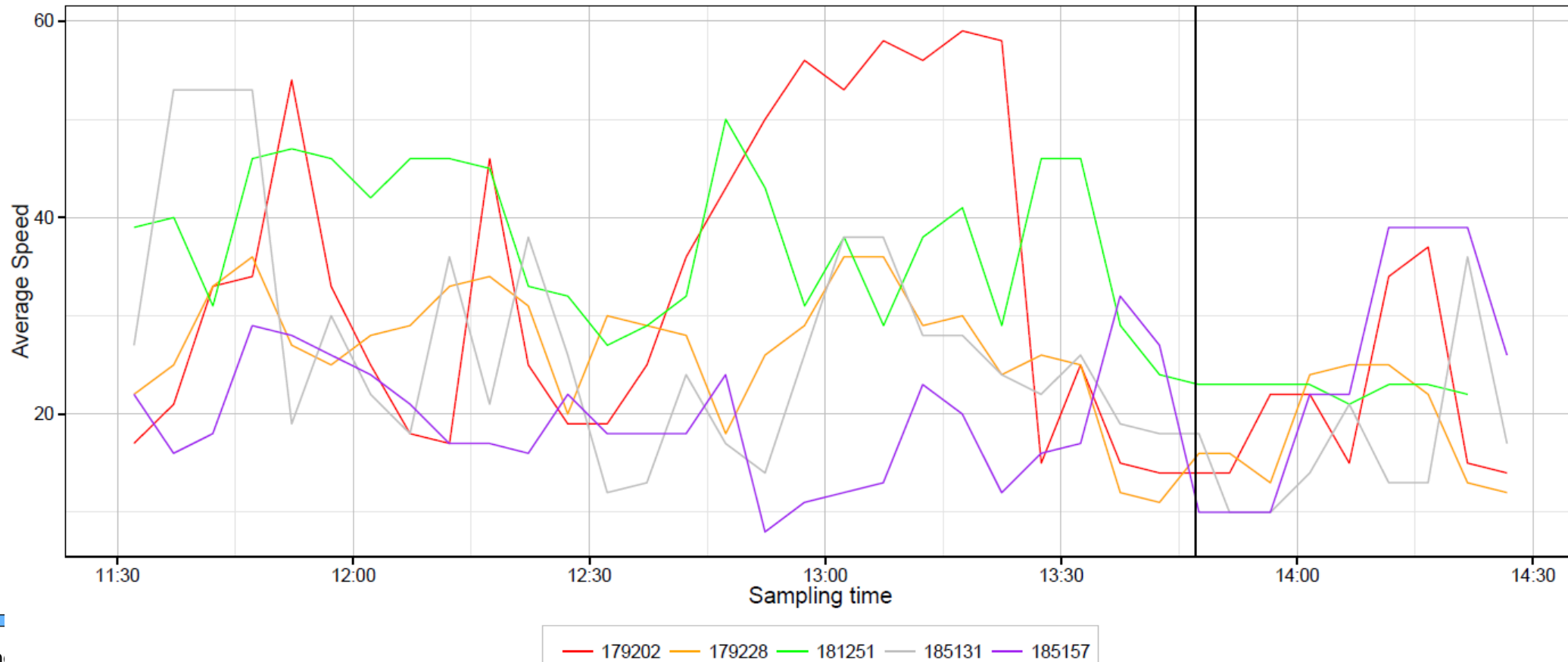
□ Example

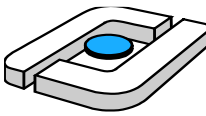
- Event location used to determine neighbouring relevant sensors
- No temporal distance effect as event is in sensor measurement area
- Analysis of time series for nearby sensors ...



□ Example

- Time series analysis
- Sensors 179202 and 179228 detecting slow traffic at event time
- ➔ assumption that event is plausible





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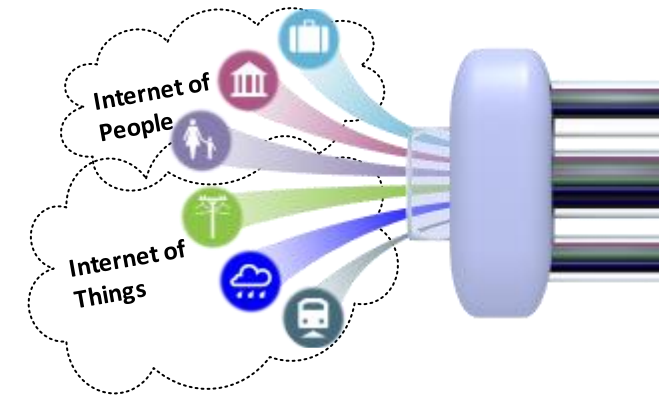
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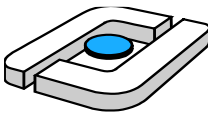
Conclusion



- ❑ Goal: Increased reliability of smart city applications
 - ❑ Measures:
 - Testing during design-time
 - Determination of required QoI for an application
 - Monitoring during run-time, separated for scalability reasons
 - Atomic Monitoring
 - Basic QoI calculation, real-time capable
 - Composite Monitoring
 - Enhanced QoI check for events, complex by using spatiotemporal related streams
- ➔ CP-framework provides extensive methods to support reliable smart city applications
- ➔ Coping error-prone and incorrect data streams
- ➔ Future: Further investigation of Composite Monitoring, apply approach to different domains (e.g. environment, noise pollution)



End



Thank you for your attention!

Questions?

